







DS26LV31T ZHCSLJ3D - MARCH 1999 - REVISED JULY 2000

# DS26LV31T 3V 增强型 CMOS 四路差动线路驱动器

# 1 特性

- 工业产品符合 TIA/EIA-422-B (RS-422) 标准和 ITU-T V.11 建议
- 军用产品符合 TIA/EIA-422-B (RS-422) 标准
- 能够与现有 5V RS-422 网络交互操作
- 工业和军用温度范围
- 在工作条件下,V<sub>OD</sub> 最小值为 2V
- 平衡输出交叉可实现低 EMI(50% 电压电平时的典 型值处于 40mV 之内)
- 低功耗设计(3.3V静态条件下为 330µW)
- 电缆 I/O 引脚上的 ESD ≥ 7kV (HBM)
- 指定的交流参数:
  - 最大驱动器偏斜:2ns - 最大转换时间:10ns
- 与 DS26C31 引脚兼容
- 断电时具有高输出阻抗
- 采用 SOIC 封装
- 标准微电路图 (SMD) 5962-98584

# 2 应用

电机控制:无刷直流和有刷直流

现场发送器:温度传感器和压力传感器

# 3 说明

DS26LV31T 是一款高速四路差分 CMOS 驱动器,同 时符合 TIA/EIA-422-B 和 ITU-T V.11 的要求。CMOS DS26LV31T 具有最大 100μA 的低静态 I<sub>CC</sub>,因此非常 适合电池供电和功耗敏感型应用。

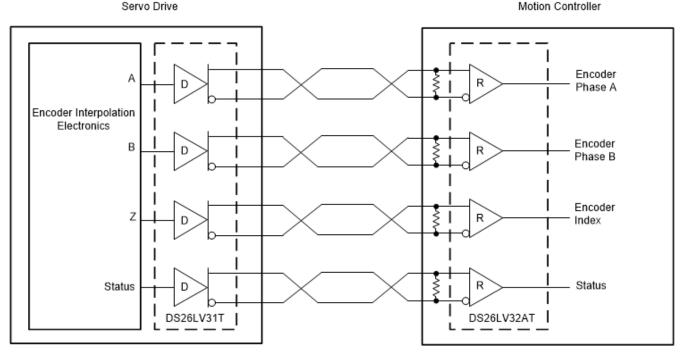
差分输出的 V<sub>OD</sub> (≥2V) 与 5V 版本相同。

EN 和 EN\* 输入可实现对 TRI-STATE 输出的低电 平有效或高电平有效控制。这些使能端由四个驱动器共 用。保护二极管可防止所有驱动器输入发生静电放电。 输出还增强了 ESD 保护,提供大于 7kV 的容差。驱 动器和使能输入(DI、EN、EN\*)与低电压 LVTTL 和 LVCMOS 器件兼容。

#### 器件信息

器件型号	<b>封装</b> <sup>(1)</sup>	封装尺寸(标称值)	
DS26LV31T	D (16)	9.90mm x 3.91mm	

如需了解所有可用封装,请参阅数据表末尾的可订购产品附 录。



应用原理图

English Data Sheet: SNLS114



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4 Revision History 注:以前版本的页码可能与当前版本的页码不同

CI	nanges from Revision C (February 2013) to Revision D (June 2020)	Page
•	添加了特性:断电时具有高输出阻抗	1
•	添加了 <i>器件信息</i> 表、ESD 等级表。热性能信息表、特性说明部分、器件功能模式、应用和实现部分、	电源
	<i>相关建议</i> 部分、 <i>布局</i> 部分、 <i>器件和文档支持</i> 部分以及 <i>机械、封装和可订购信息</i> 部分	1
CI	nanges from Revision B (March 1999) to Revision C (February 2013)	Page
•	已将国家数据表的版面布局更改为 TI 格式	1



# **5 Pin Configuration and Functions**

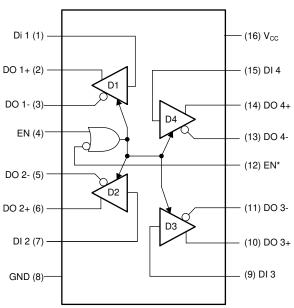


图 5-1. Dual-In-Line Package (Top View)

#### **Pin Functions**

PI	PIN		PIN		DESCRIPTION
NAME	NO.	I/O <sup>(1)</sup>	DESCRIPTION		
DI 1	1	I	Driver 1 input		
DO 1+	2	0	Driver 1 output		
DO 1-	3	0	Driver 1 inverted output		
EN	4	ı	Active high enable		
DO 2-	5	0	Driver 2 inverted output		
DO 2+	6	0	Driver 2 output		
DI 2	7	I	Driver 2 input		
GND	8	G	Ground pin		
DI 3	9	ı	Dirver 3 input		
DO 3+	10	0	Driver 3 output		
DO 3-	11	0	Driver 3 inverted output		
EN*	12	I	Active low enable		
DO 4-	13	0	Driver 4 inverted output		
DO 4+	14	0	Driver 4 output		
DI 4	15	ı	Driver 4 input		
V <sub>CC</sub>	16	Р	Power pin		

<sup>(1)</sup> I = Input, O = Output, I/O = Input or Output, G = Ground, P = Power.



# **6 Specifications**

over operating free-air temperature range (unless otherwise noted)(1) (2)

# **6.1 Absolute Maximum Ratings**

		MIN	MAX	UNIT
V <sub>CC</sub>	Supply Voltage	-0.5	7	V
EN, EN*	Enable Input Voltage	-0.5	V <sub>CC</sub> + 0.5	V
DI	Driver Input Voltage	-0.5	V <sub>CC</sub> + 0.5	V
	Clamp Diode Current	-20	20	mA
	DC Output Current, per pin	-150	150	mA
	Driver Output Voltage			
	(Power Off: DO+, DO-)	-0.5	7	V
T <sub>stg</sub>	Storage temperature	-65	150	°C

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

# 6.2 ESD Ratings

				VALUE	UNIT
V	Electrostatic discharge	Human-body model (HBM), per ANSI/ESDA/JEDEC	Driver output pins	±7000	V
(ESD)	V <sub>(ESD)</sub> Electrostatic discharge	JS-001 <sup>(1)</sup>	Other pins	±2500	] V

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

over operating free-air temperature range (unless otherwise noted)

## **6.3 Recommended Operating Conditions**

			MIN	NOM	MAX	UNIT
V <sub>CC</sub>	Supply Voltage		3	3.3	3.6	V
т.	Operating Free Air Temperature Range	DS26LV31T	-40	25	85	°C
I A		DS26LV31W	-55	25	125	°C
	Input Rise and Fall Time				500	ns

#### **6.4 Thermal Resistance Characteristics**

		DS26LV31T	
THERMAL METRIC	(1)	SOIC (D)	UNIT
		16 Pins	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	73.6	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	32.5	°C/W
R <sub>θJC</sub>	Junction-to-board thermal resistance	31.1	°C/W
Ψ ЈТ	Junction-to-top characterization parameter	3.7	°C/W
Ψ ЈВ	Junction-to-board characterization parameter	30.8	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	n/a	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC package thermal metrics application report.

Product Folder Links: DS26LV31T

<sup>(2)</sup> If Military/Aerospace specified devices are required, please contact the TI Sales Office/Distributors for availability and specifications.



over operating free-air temperature range (unless otherwise noted)(1) (2)

## **6.5 Electrical Characteristics**

	PARAMETER	TEST CONDITIONS		Pin	MIN	TYP	MAX	UNIT
V <sub>OD1</sub>	Output Differential Voltage	R <sub>L</sub> = ∞ (No Load)				3.3	4	V
V <sub>OD2</sub>	Output Differential Voltage	R <sub>L</sub> = 100 Ω (图 7-1),		1	2	2.6		V
$\Delta V_{OD2}$	Change in Magnitude of Output Differential Voltage	$R_L = 100 \Omega \text{ (ss. 7-1)},$ $I_O \ge 20 \text{ mA}$			-400	7	400	mV
V <sub>OD3</sub>	Output Differential Voltage	R <sub>L</sub> = 3900 Ω (V.11) $\blacksquare$ 7-1 and <sup>(3)</sup>				3.2	3.6	V
V <sub>OC</sub>	Common Mode Voltage				,	1.5	2	V
ΔV <sub>OC</sub>	Change in Magnitude of Common Mode Voltage	R <sub>L</sub> = 100 Ω (图 7-1)		DO+.	-400	6	400	mV
l <sub>OZ</sub>	TRI-STATE Leakage Current	V <sub>OUT</sub> = V <sub>CC</sub> or GND [	Drivers Disabled	DO-		±0.5	±20	μA
	Output Short Circuit Current	V <sub>OUT</sub> = 0 V	$T_A = -40$ °C to +85°C		-40	-70	-150	mA
I <sub>SC</sub>		$V_{IN} = V_{CC}$ or GND <sup>(4)</sup>	$T_A = -55^{\circ}C$ to $+125^{\circ}C$ (5)		-30		-160	mA
	Output Leakage Current	V <sub>CC</sub> = 0 V, V <sub>OUT</sub> = 3 V or 6 V		1		0.03	100	μA
I <sub>OFF</sub>		Output Leakage Current $V_{CC} = 0 V$ ,	T <sub>A</sub> = -40°C to +85°C			-0.08	-100	μA
		$V_{OUT} = -0.25 \text{ V}$	T <sub>A</sub> = -55°C to +125°C				-200	μΑ
V <sub>IH</sub>	High Level Input Voltage				2		V <sub>CC</sub>	V
V <sub>IL</sub>	Low Level Input Voltage			] [	GND		0.8	V
I <sub>IH</sub>	High Level Input Current	V <sub>IN</sub> = V <sub>CC</sub>		DI, EN, EN*			10	μΑ
I <sub>IL</sub>	Low Level Input Current	V <sub>IN</sub> = GND			-10			μΑ
$V_{CL}$	Input Clamp Voltage	I <sub>IN</sub> = −18 mA		1			-1.5	V
1	Power Supply Current	No Load, $V_{IN}$ (all) = $V_{CC}$ or GND	T <sub>A</sub> = -40°C to +85°C	V			100	μΑ
I <sub>CC</sub>	Power Supply Current		T <sub>A</sub> = -55°C to +125°C	V <sub>CC</sub>			125	μΑ

<sup>(1)</sup> Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except differential voltages  $V_{OD1}$ ,  $V_{OD2}$ ,  $V_{OD3}$ . All typicals are given for  $V_{CC}$  = +3.3 V,  $T_A$  = +25°C. This specification limit is for compliance with TIA/EIA-422-B and ITU-T V.11.

<sup>(3)</sup> 

 <sup>(4)</sup> Only one output shorted at a time. The output (true or complement) is configured High.
 (5) This parameter does not meet the TIA/EIA-422-B specification.



over operating free-air temperature range (unless otherwise noted)(1) (2)

# 6.6 Switching Characteristics - Industrial DS26LV31T

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>PHLD</sub>	Differential Propagation Delay High to Low		6	10.5	16	ns
t <sub>PLHD</sub>	Differential Propagation Delay Low to High		6	11	16	ns
t <sub>SKD</sub>	Differential Skew (same channel)   t <sub>PHLD</sub> - t <sub>PLHD</sub>	$R_L = 100 \Omega, C_L = 50 pF$		0.5	2	ns
t <sub>SK1</sub>	Skew, Pin to Pin (same device)	图 7-2 and 图 7-3)		1	2	ns
t <sub>SK2</sub>	Skew, Part to Part (3)			3	5	ns
t <sub>TLH</sub>	Differential Transition Time Low to High (20% to 80%)			4.2	10	ns
t <sub>THL</sub>	Differential Transition Time High to Low (80% to 20%)			4.7	10	ns
t <sub>PHZ</sub>	Disable Time High to Z			12	20	ns
t <sub>PLZ</sub>	Disable Time Low to Z			9	20	ns
t <sub>PZH</sub>	Enable Time Z to High	- (图 7-4 and 图 7-5)		22	32	ns
t <sub>PZL</sub>	Enable Time Z to Low			22	32	ns
f <sub>max</sub>	Maximum Operating Frequency (4)		32			MHz

- (1) f = 1 MHz,  $t_r$  and  $t_f \le 6 \text{ ns}$ , 10% to 90%.
- (2) See TIA/EIA-422-B specifications for exact test conditions.
- (3) Devices are at the same V<sub>CC</sub> and within 5°C within the operating temperature range.
- (4) All channels switching, output duty cycle criteria is 40%/60% measured at 50%. This parameter is specified by design and characterization.

over operating free-air temperature range (unless otherwise noted) (1) (2)

# 6.7 Switching Characteristics - Military DS26LV31W

	PARAMETER	TEST CONDITIONS	MIN	TYP MAX	UNIT
t <sub>PHLD</sub>	Differential Propagation Delay High to Low	R <sub>L</sub> = 100 Ω, C <sub>L</sub> = 50 pF ( $\upred{8}$ 7-2 and $\upred{8}$ 7-3)	5	25	ns
t <sub>PLHD</sub>	Differential Propagation Delay Low to High		5	25	ns
t <sub>SKD</sub>	Differential Skew (same channel)   t <sub>PHLD</sub> - t <sub>PLHD</sub>			5	ns
t <sub>SK1</sub>	Skew, Pin to Pin (same device)			5	ns
t <sub>PHZ</sub>	Disable Time High to Z			35	ns
t <sub>PLZ</sub>	Disable Time Low to Z			35	ns
t <sub>PZH</sub>	Enable Time Z to High			40	ns
t <sub>PZL</sub>	Enable Time Z to Low			40	ns

- (1)  $f = 1 \text{ MHz}, t_r \text{ and } t_f \le 6 \text{ ns}, 10\% \text{ to } 90\%.$
- (2) See TIA/EIA-422-B specifications for exact test conditions.

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# **6.8 Typical Characteristics**

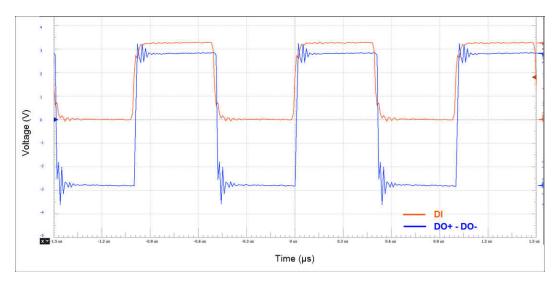


图 6-1. Voltage vs Time



## 7 Parameter Measurement Information

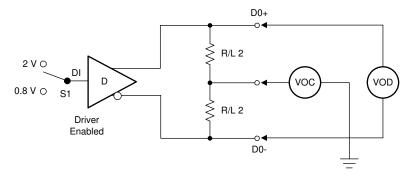


图 7-1. Differential Driver DC Test Circuit

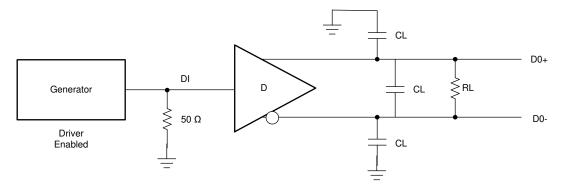
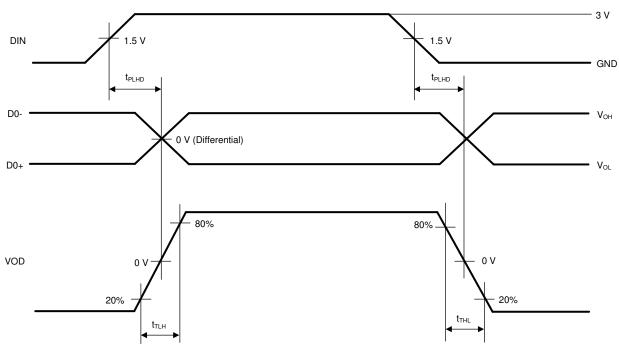


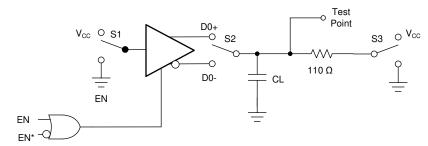
图 7-2. Differential Driver Propagation Delay and Transition Time Test Circuit



- A. Generator waveform for all tests unless otherwise specified: f = 1 MHz, Duty Cycle = 50%  $Z_O = 50 \Omega$ ,  $t_r \le 10$  ns,  $t_f \le 10$ .
- B. C<sub>L</sub> includes probe and fixture capacitance

图 7-3. Differential Driver Propagation Delay and Transition Time Waveforms





- A. If EN is the input, then EN\* = High
- B. If EN\* is the input, then EN = Low

图 7-4. Driver Single-Ended TRI-STATE Test Circuit

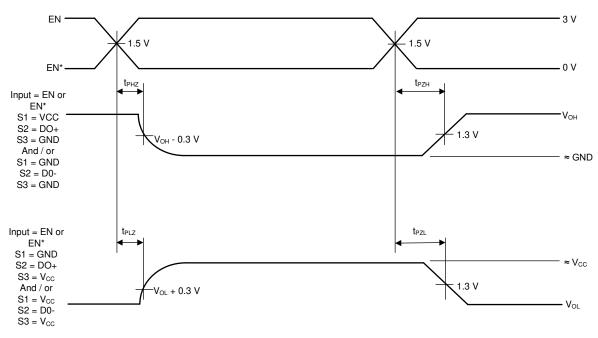


图 7-5. Driver Single-Ended TRI-STATE Waveforms

 $V_{\text{OL}} \\$ 

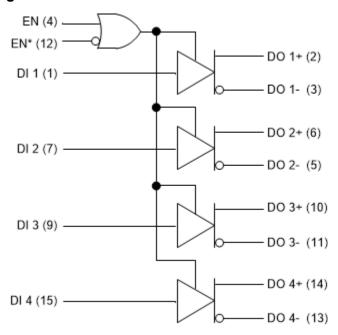


# **8 Detailed Description**

## 8.1 Overview

The DS26LV31T is a high speed CMOS quadruple differential line drivers with 3-state outputs. The devices are designed to be similar to TIA/EIA-422-B and ITU Recommendation V.11 drivers with a single 3.3-V power supply. The drivers also integrate active-high and active-low enables for precise device control.

#### 8.2 Functional Block Diagram



#### 8.3 Feature Description

The devices can be configured using the EN and EN\* logic inputs to select transmitter output. A logic high on the EN pin or a logic low on the EN\* pin enables the device to operate. These pins are simply a way to configure the logic to match that of the receiving or transmitting controller or microprocessor.

The DS26LV31T are optimized for balanced-bus transmission at switching rates up to 32 MHz.

The CMOS DS26LV31T consumes low static  $I_{CC}$  of 100 uA MAX that makes it ideal for battery powered applications.

#### 8.4 Device Functional Modes

表 8-1. Truth Table

Enables <sup>(1)</sup>		lput	Outputs	
EN	EN*	DI	DO+	DO-
L	Н	Х	Z	Z
All other combinations of enable inputs		L	L	Н
		Н	Н	L

(1) L = Low logic state, X = Irrelevant, H = High logic state, Z = TRI-STATE

Motion Controller



# 9 Application and Implementation

Servo Drive

#### 备注

以下应用部分中的信息不属于 TI 器件规格的范围,TI 不担保其准确性和完整性。TI 的客 户应负责确定 器件是否适用于其应用。客户应验证并测试其设计,以确保系统功能。

### 9.1 Application Information

When designing a system that uses drivers, receivers, and transceivers, proper cable termination is essential for highly reliable applications with reduced reflections in the transmission line. If termination is used, it can be placed at the end of the cable near the last receiver. A single driver and receiver, TI DS26LV31T and DS26LV32AT, respectively, were tested at room temperature with a 3.3-V supply voltage. For laboratory experiments, 100 feet of 120-Ω, 24-AWG, twisted-pair cable (Bertek) was used. The communication was succssful with 1Mbps data rate.

### 9.2 Typical Application

#### 9.2.1 Application

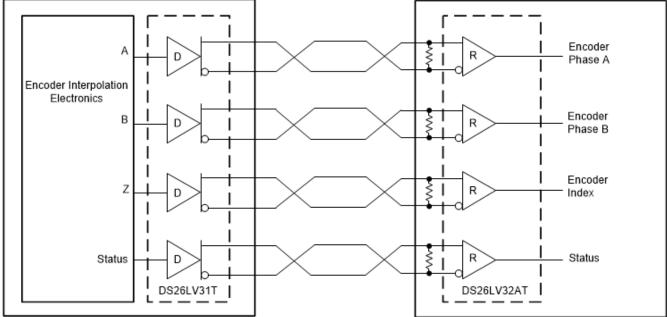


图 9-1. Application Schematic - Encoder Application

#### 9.2.2 Design Requirements

Resistor and capacitor (if used) termination values are shown for each laboratory experiment, but vary from system to system. For example, the termination resistor, RT, must be within 20% of the characteristic impedance, Zo, of the cable and can vary from about 80  $\Omega$  to 120  $\Omega$ .

This example requires the following:

- 3.3-V power source
- RS-485 bus operating at 32 MHz or less
- Connector that ensures the correct polarity for port pins

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#### 9.2.3 Detailed Design Procedure

Ensure values in Absolute Maximum Ratings are not exceeded. Supply voltage, VIH, and VIL must comply with Recommended Operating Conditions. Place the device close to bus connector to keep traces (stub) short to prevent adding reflections to the bus line. If desired, add external fail-safe biasing to ensure 200 mV on the A-B port, if the drive is in high impedance state.

General application guidelines and hints for differential drivers and receivers may be found in the following application notes:

- AN-214 Transmission Line Drivers and Receivers for TIA/EIA Standards RS-422 and RS-423
- AN-457 High Speed, Low Skew RS-422 Drivers and Receivers Solve Critical System Timing Problems
- AN-805 Calculating Power Dissipation for Differential Line Drivers
- AN-847 FAILSAFE Biasing of Differential Buses
- AN-903 A Comparison of Differential Termination
- AN-912 Common Data Transmission Parameters and their Definitions
- AN-916 A Practical Guide To Cable Selection

#### 9.2.3.1 Power Decoupling Recommendations

Bypass caps must be used on power pins. High frequency ceramic (surface mount is recommended) 0.1  $\mu$ F in parallel with 0.01  $\mu$ F at the power supply pin. A 10  $\mu$ F or greater solid tantalum or electrolytic should be connected at the power entry point on the printed circuit board.

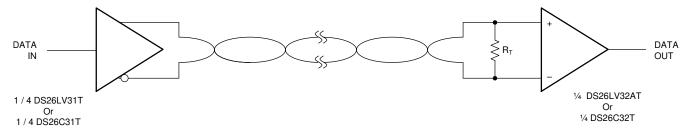


图 9-2. Typical Driver Connection - R<sub>T</sub> is optional although highly recommended to reduce reflection

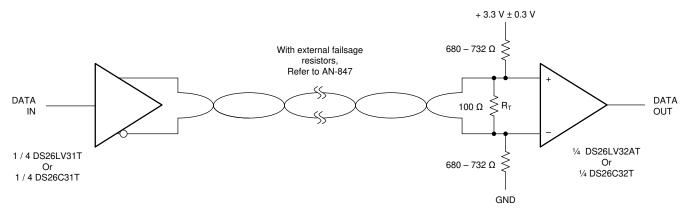


图 9-3. Typical Driver Connection



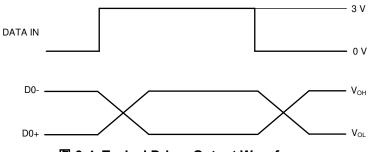


图 9-4. Typical Driver Output Waveforms

## 9.2.4 Application Performance Plots

Differential 120-Ω Terminated Output Waveforms (Cat 5E Cable). The DO measured at the TX end

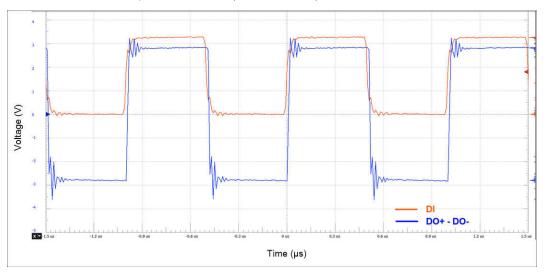


图 9-5. Voltage vs Time

# 10 Power Supply Recommendations

Place a 0.1- $\mu$ F bypass capacitors close to the power-supply pins to reduce errors coupling in from noisy or high impedance power supplies.



# 11 Layout

# 11.1 Layout Guidelines

For best operational performance of the device, use good PCB layout practices, including:

- Noise can propagate into analog circuitry through the power pins of the circuit as a whole, as well as the
  operational amplifier. Bypass capacitors are used to reduce the coupled noise by providing low impedance
  power sources local to the analog circuitry. Connect low-ESR, 0.1-µF ceramic bypass capacitors between
  supply pin and ground, placed as close to the device as possible.
- Separate grounding for analog and digital portions of circuitry is one of the simplest and most effective methods of noise suppression. One or more layers on multilayer PCBs are usually devoted to ground planes. A ground plane helps distribute heat and reduces EMI noise pickup. Make sure to physically separate digital and analog grounds, paying attention to the flow of the ground current.
- To reduce parasitic coupling, run the input traces as far away from the supply or output traces as possible. If it is not possible to keep them separate, it is much better to cross the sensitive trace perpendicular as opposed to in parallel with the noisy trace.
- Keep the length of input traces as short as possible. Always remember that the input traces are the most sensitive part of the circuit.
- Consider a driven, low-impedance guard ring around the critical traces. A guard ring can significantly reduce leakage currents from nearby traces that are at different potentials.

### 11.2 Layout Example

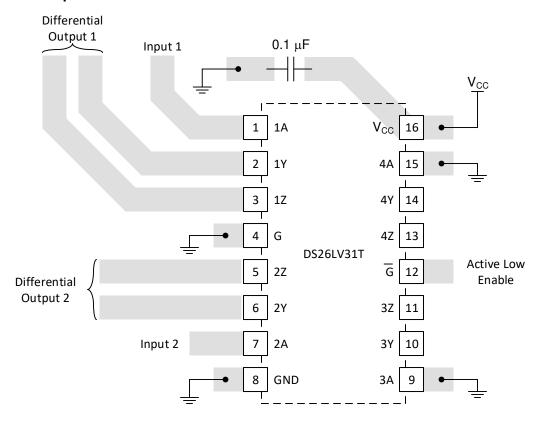


图 11-1. Trace Layout on PCB and Recommendations

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# 12 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

#### **12.1 Documentation Support**

#### 12.2 接收文档更新通知

要接收文档更新通知,请导航至 ti.com 上的器件产品文件夹。点击*订阅更新* 进行注册,即可每周接收产品信息更 改摘要。有关更改的详细信息,请查看任何已修订文档中包含的修订历史记录。

#### 12.3 支持资源

TI E2E™ 支持论坛是工程师的重要参考资料,可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题可获得所需的快速设计帮助。

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#### 12.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

所有商标均为其各自所有者的财产。

### 12.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 12.6 术语表

#### TI术语表

本术语表列出并解释了术语、首字母缩略词和定义。

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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#### PACKAGING INFORMATION

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
DS26LV31TM/NOPB	LIFEBUY	SOIC	D	16	48	RoHS & Green		Level-1-260C-UNLIM	-40 to 85	DS26LV31 TM	
DS26LV31TMX/NOPB	LIFEBUY	SOIC	D	16	2500	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 85	DS26LV31 TM	

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

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# **PACKAGE OPTION ADDENDUM**

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# **PACKAGE MATERIALS INFORMATION**

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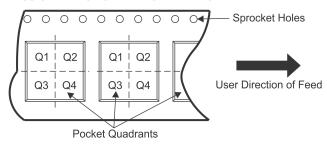
# TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

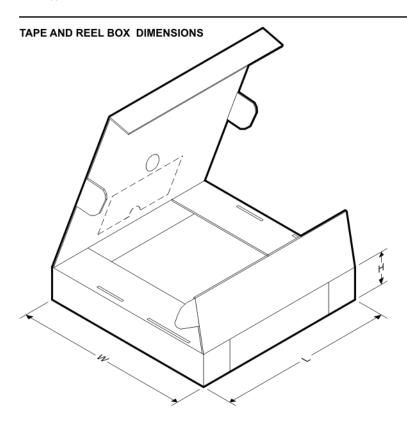
## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DS26LV31TMX/NOPB	SOIC	D	16	2500	330.0	16.4	6.5	10.3	2.3	8.0	16.0	Q1

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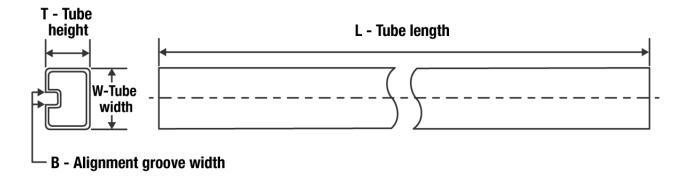
#### \*All dimensions are nominal

Device		Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ı	DS26LV31TMX/NOPB	SOIC	D	16	2500	367.0	367.0	35.0

# PACKAGE MATERIALS INFORMATION

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## **TUBE**



#### \*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (µm)	B (mm)
DS26LV31TM/NOPB	D	SOIC	16	48	495	8	4064	3.05

# D (R-PDS0-G16)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AC.



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