

# TPS55065-Q1 Buck and Boost Switched-Mode Regulator

## 1 Features

- Qualified for Automotive Applications
- AEC-Q100 Qualified With the Following Results
  - Device Temperature Grade 1: –40°C to +125°C Ambient Operating Temperature Range
  - Device HBM ESD Classification Level 1B
  - Device CDM ESD Classification Level C4B
- Switched-Mode Regulator
  - 5 V ±2%, Normal Mode
  - 5 V ±3%, Low-Power or Crossover Mode
- Switching Frequency, 440 kHz (Typical)
- Input Operating Range, 1.5 V to 40 V, ( $V_{driver}$ )
  - 500-mA Load-Current Capability
  - 200-mA Load-Current Capability Down to 2-V Input ( $V_{driver}$ )
  - 120-mA Load-Current Capability Down to 1.5-V Input ( $V_{driver}$ )
- Enable Function
- Low-Power Operation Mode
- Switched 5-V Regulated Output on 5Vg With Current Limit
- Programmable Slew Rate and Frequency Modulation for EMI Consideration
- Reset Function With Deglitch Timer and Programmable Delay
- Alarm Function for Undervoltage Detection and Indication
- Thermally Enhanced Package for Efficient Heat Management

## 2 Applications

- Automotive Infotainment and Cluster
- 12-V Industrial Power Systems
- Servers

## 3 Description

The TPS55065 is a switched-mode regulator with integrated switches for voltage-mode control. With the aid of external components (LC combination), the device regulates the output to 5 V ±3% for a wide input-voltage range.

The TPS55065 device offers a reset function to detect and indicate when the 5-V output rail is outside of the specified tolerance. This reset delay is programmable using an external timing capacitor on the REST terminal. Additionally, an alarm ( $A_{OUT}$ ) feature is activated when the input supply rail  $V_{driver}$  is below a prescaled specified value (set by the  $A_{IN}$  terminal).

The TPS55065 device has a frequency-modulation scheme to minimize EMI. The clock modulator permits a modulation of the switching frequency to reduce interference energy in the frequency band.

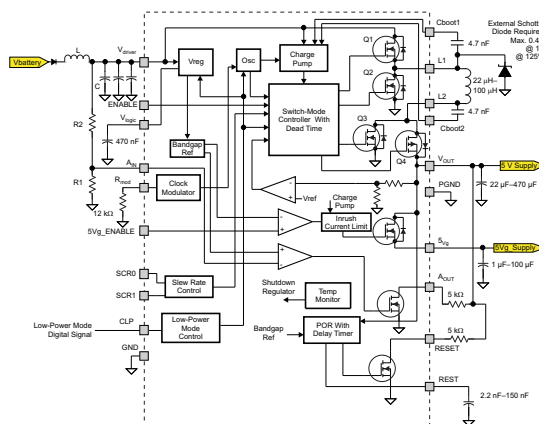
The 5-Vg output is a switched 5-V regulated output with internal current limiting to prevent assertion of RESET when powering a capacitive load on the supply line. This function is controlled by the 5Vg\_ENABLE terminal. If there is a short to ground on this output (5Vg output), the output self-protects by operating in a chopping mode. This does, however, increase the output ripple voltage on  $V_{OUT}$  during this fault condition.

### Device Information<sup>(1)</sup>

| PART NUMBER | PACKAGE     | BODY SIZE (NOM)   |
|-------------|-------------|-------------------|
| TPS55065-Q1 | HTSSOP (20) | 6.50 mm x 4.40 mm |

(1) For all available packages, see the orderable addendum at the end of the data sheet.

### Simplified Schematic



All component values are typical.

## Table of Contents

|  |           |  |           |
|--|-----------|--|-----------|
| <b>1 Features</b> .....                        | <b>1</b>  | 7.2 Functional Block Diagram .....                               | <b>11</b> |
| <b>2 Applications</b> .....                    | <b>1</b>  | 7.3 Feature Description .....                                    | <b>12</b> |
| <b>3 Description</b> .....                     | <b>1</b>  | 7.4 Device Functional Modes .....                                | <b>15</b> |
| <b>4 Revision History</b> .....                | <b>2</b>  | <b>8 Application and Implementation</b> .....                    | <b>18</b> |
| <b>5 Pin Configuration and Functions</b> ..... | <b>3</b>  | 8.1 Application Information .....                                | <b>18</b> |
| <b>6 Specifications</b> .....                  | <b>4</b>  | 8.2 Typical Application .....                                    | <b>18</b> |
| 6.1 Absolute Maximum Ratings .....             | <b>4</b>  | <b>9 Power Supply Recommendations</b> .....                      | <b>20</b> |
| 6.2 ESD Ratings .....                          | <b>4</b>  | <b>10 Layout</b> .....   | <b>20</b> |
| 6.3 Recommended Operating Conditions .....     | <b>4</b>  | 10.1 Layout Guidelines .....                                     | <b>20</b> |
| 6.4 Thermal Information .....                  | <b>5</b>  | 10.2 Layout Example .....  | <b>21</b> |
| 6.5 Dissipation Ratings .....                  | <b>5</b>  | <b>11 Device and Documentation Support</b> .....                 | <b>24</b> |
| 6.6 Electrical Characteristics .....           | <b>6</b>  | 11.1 Documentation Support .....                                 | <b>24</b> |
| 6.7 Switching Characteristics .....            | <b>7</b>  | 11.2 Trademarks .....  | <b>24</b> |
| 6.8 Typical Characteristics .....              | <b>8</b>  | 11.3 Electrostatic Discharge Caution .....                       | <b>24</b> |
| <b>7 Detailed Description</b> .....            | <b>11</b> | 11.4 Glossary .....  | <b>24</b> |
| 7.1 Overview .....                             | <b>11</b> | <b>12 Mechanical, Packaging, and Orderable Information</b> ..... | <b>24</b> |

## 4 Revision History

### Changes from Original (October 2008) to Revision A

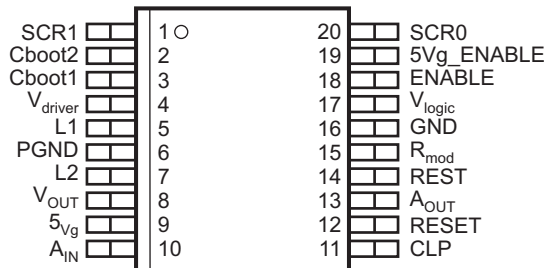
**Page**

- Added *ESD Ratings* table, *Feature Description* section, *Device Functional Modes*, *Application and Implementation* section, *Power Supply Recommendations* section, *Layout* section, *Device and Documentation Support* section, and *Mechanical, Packaging, and Orderable Information* section .....

**4**

## 5 Pin Configuration and Functions

**PWP HTSSOP Package  
20 Pins  
Top View**



**Pin Functions**

| PIN                 |     | I/O | DESCRIPTION   |
|---------------------|-----|-----|---|
| NAME                | NO. |     |   |
| SCR1                | 1   | I   | Programmable slew-rate control  |
| Cboot2              | 2   | I   | External bootstrap capacitor  |
| Cboot1              | 3   | I   | External bootstrap capacitor  |
| V <sub>driver</sub> | 4   | I   | Input voltage source  |
| L1                  | 5   | I   | Inductor input (an external Schottky diode <sup>(1)</sup> to GND must be connected to L1) |
| PGND                | 6   | I   | Power ground  |
| L2                  | 7   | I   | Inductor output   |
| V <sub>OUT</sub>    | 8   | O   | 5-V regulated output  |
| 5Vg                 | 9   | O   | Switched 5-V supply   |
| A <sub>IN</sub>     | 10  | I   | Programmable alarm setting  |
| CLP                 | 11  | I/O | Low-power operation mode (digital input)  |
| RESET               | 12  | O   | Reset function (open drain)   |
| A <sub>OUT</sub>    | 13  | O   | Alarm output (open drain)   |
| REST                | 14  | O   | Programmable reset timer delay  |
| R <sub>mod</sub>    | 15  | I   | Main switching frequency modulation setting to minimize EMI                               |
| GND                 | 16  | I   | Ground  |
| V <sub>logic</sub>  | 17  | O   | Supply decoupling output (may be used as a 5-V supply for logic-level inputs)             |
| ENABLE              | 18  | I   | Switched-mode regulator enable/disable  |
| 5Vg_ENABLE          | 19  | I   | Switched 5-V voltage regulator output enable/disable                                      |
| SCR0                | 20  | I   | Programmable slew-rate control  |
| Exposed thermal pad | —   | —   | Connect to GND or left floating.  |

(1) Maximum 0.4 V at 1 A at 125°C

## 6 Specifications

### 6.1 Absolute Maximum Ratings

 over operating free-air temperature range (unless otherwise noted) <sup>(1)</sup>

|   |  | MIN                                     | MAX | UNIT |
|---|--|---|-----|------|
| $V_{(driver)}$ <sup>(2)</sup>   | Unregulated input voltage,             | -0.5                                    | 40  | V    |
| $V_{(AIN)}$ , $V_{(ENABLE)}$ <sup>(2)</sup>   | Unregulated inputs                     | -0.5                                    | 40  | V    |
| $V_{(Cboot1)}$  | Bootstrap voltages                     |   | 52  | V    |
| $V_{(Cboot2)}$  |  |   | 14  | V    |
| $V_{(L1)}$  | Switch mode voltages                   | -1                                      | 40  | V    |
| $V_{(L2)}$  |  | -1                                      | 7   | V    |
| $V_{(Rmod)}$ , $V_{(SCR0)}$ , $V_{(SCR1)}$ ,<br>$V_{(CLP)}$ , and<br>$V_{(5Vg\_ENABLE)}$ <sup>(2)</sup> | Logic input voltages                   | -0.5                                    | 7   | V    |
| $V_{(RESET)}$ , $V_{(AOUT)}$ , $V_{(logic)}$ ,<br>and $V_{(REST)}$ <sup>(2)</sup>                       | Low output voltages                    | -0.5                                    | 7   | V    |
| $P_D$   | Continuous power dissipation           | See <a href="#">Dissipation Ratings</a> |     |      |
| $T_J$   | Operating virtual junction temperature | -40                                     | 150 | °C   |
| $T_A$   | Operating ambient temperature          | -40                                     | 125 | °C   |
| $T_{stg}$   | Storage temperature                    | -65                                     | 125 | °C   |

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to ground.

### 6.2 ESD Ratings

|                                     |  |   | VALUE | UNIT |
|-------------------------------------|--|---|-------|------|
| $V_{(ESD)}$ Electrostatic discharge | Human body model (HBM), per AEC Q100-002 <sup>(1)(2)</sup> | Classification 1B for pin 7, pin 8, pin 9     | ±800  | V    |
|                                     |  | Classification 2 for pins 1 to 6 and 10 to 20 | ±2000 |      |
|                                     | Charged device model (CDM), per AEC Q100-011               | Classification Level C4B for All pins         | ±750  |      |

(1) AEC Q100-002 indicates HBM stressing is done in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

(2) The human body model is a 100-pF capacitor discharged through a 1.5-kΩ resistor into each terminal.

### 6.3 Recommended Operating Conditions

|  |                | MIN           | NOM                 | MAX           | UNIT |
|--|----------------|---------------|---------------------|---------------|------|
| Unregulated input voltage, $V_{(driver)}$  |                | 6             |                     | 24            | V    |
| Unregulated input voltages, $V_{(AIN)}$ and $V_{(ENABLE)}$   |                | 0             |                     | 24            | V    |
| Switched-mode terminals  | $V_{(L1)}$     | -1            |                     | 17            | V    |
|  | $V_{(L2)}$     | 5             |                     | 5.5           |      |
| Bootstrap voltages   | $V_{(Cboot1)}$ |               | $V_{(driver)} + 10$ |               | V    |
|  | $V_{(Cboot2)}$ |               | 8                   |               |      |
| Logic levels (I/O), $V_{(Rmod)}$ , $V_{(logic)}$ , $V_{(SCR0)}$ , $V_{(SCR1)}$ , $V_{(5Vg\_ENABLE)}$ , $V_{(RESET)}$ , $V_{(AOUT)}$ , $V_{(CLP)}$ , and $V_{(REST)}$ |                | 0             |                     | 5.25          | V    |
| Operating ambient temperature range, $T_A$   |                | -40           |                     | 125           | °C   |
| Logic levels (I/O), $V_{(SCR0)}$ , $V_{(SCR1)}$ , $V_{(CLP)}$ directly connected to $V_{(logic)}$  |                | $V_{(logic)}$ |                     | $V_{(logic)}$ | V    |

## 6.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup> |  | TPS55065-Q1  | UNIT |
|-------------------------------|--|--------------|------|
|                               |  | PWP [HTSSOP] |      |
|                               |  | 20 PINS      |      |
| $R_{\theta JA}$               | Junction-to-ambient thermal resistance       | 37.9         | °C/W |
| $R_{\theta JC(top)}$          | Junction-to-case (top) thermal resistance    | 22.7         |      |
| $R_{\theta JB}$               | Junction-to-board thermal resistance         | 20.2         |      |
| $\psi_{JT}$                   | Junction-to-top characterization parameter   | 0.7          |      |
| $\psi_{JB}$                   | Junction-to-board characterization parameter | 19.9         |      |
| $R_{\theta JC(bot)}$          | Junction-to-case (bottom) thermal resistance | 1.8          |      |

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).

## 6.5 Dissipation Ratings

| $R_{\theta JA}$ | POWER RATING<br>$T_A \leq 25^\circ\text{C}$ | DERATING FACTOR ABOVE<br>$T_A = 25^\circ\text{C}$ | POWER RATING<br>$T_A = 85^\circ\text{C}$ | POWER RATING<br>$T_A = 125^\circ\text{C}$ |
|-----------------|---|---|--|---|
| 32°C/W          | 3.9 W                                       | 31.25 mW/°C                                       | 2.03 W                                   | 0.781 W                                   |
| 40°C/W          | 3.125 W                                     | 25 mW/°C  | 1.625 W                                  | 0.625 W                                   |

## 6.6 Electrical Characteristics

 $V_{(driver)} = 6\text{ V to }17\text{ V}$ ,  $T_A = -40^\circ\text{C to }125^\circ\text{C}$ , unless otherwise noted

| PARAMETER                    |  | TEST CONDITIONS   | MIN  | TYP | MAX   | UNIT             |
|------------------------------|--|---|------|-----|-------|------------------|
| $V_{(driver)}$               | Unregulated input voltage                    |   | 1.5  |     | 40    | V                |
| $V_{(driver)}$               | Start-up condition voltage                   | $I_O = 500\text{ mA}$   |      |     | 5     | V                |
| $S_{OM}$                     | Soft-start ramp                              | $C_O = 36\text{ }\mu\text{F}$ (minimum) to $220\text{ }\mu\text{F}$ (maximum)                   | 4    |     | 20    | V/ms             |
|                              |  | $C_O = 220\text{ }\mu\text{F}$ (min) to $470\text{ }\mu\text{F}$ (max), see Note <sup>(1)</sup> | 2    |     | 20    |                  |
| $I_{(standby)}$              | Standby current                              | ENABLE = low  |      | 10  | 20    | $\mu\text{A}$    |
| $I_q$                        | Quiescent current                            | CLP = 0 V, $V_{(driver)} = 11\text{ V}$ , $I_O = 0\text{ mA}$                                   |      | 100 | 160   | $\mu\text{A}$    |
| $V_O$                        | Output voltage                               | DC  |      | 5   |       | V                |
| $V_O$                        | Output-voltage tolerance                     | Normal mode   |      |     | 2%    |                  |
|                              |  | Boost/buck crossover or low-power mode  |      |     | 3%    |                  |
| $I_O$                        | Output current                               | $V_{(driver)} \geq 7\text{ V}$  |      |     | 0.5   | A                |
| $I_{O(Boost)}$               | Output current, boost mode                   | $V_{(driver)} = 2\text{ V}$ , see Note <sup>(2)</sup>   |      |     | 200   | mA               |
|                              |  | $V_{(driver)} = 1.5\text{ V}$ , see Note <sup>(2)</sup>   |      |     | 120   |                  |
| $I_{PPn}$                    | Internal peak current limit (normal mode)    | See <sup>(1)</sup>  | 1.75 |     | 2.5   | A                |
| $I_{PPI}$                    | Internal peak current limit (low-power mode) | See <sup>(1)</sup>  | 0.75 |     | 1.25  | A                |
| $I_P$                        | Peak current                                 | $V_{(driver)} = 16\text{ V}$ , $I_O = 500\text{ mA}$ , $L = 33\text{ }\mu\text{H}$              |      | 1.5 |       | A                |
| $V_{(driver)}$               | Boost/buck crossover voltage window          | See <sup>(3)</sup>  | 5    |     | 5.9   | V                |
| $T_{ot}$                     | Thermal shutdown <sup>(4)</sup>              |   | 160  | 180 | 200   | $^\circ\text{C}$ |
| <b>5Vg OUTPUT AND ENABLE</b> |  |   |      |     |       |                  |
| $r_{DS(on)}$                 | On-state resistance                          |   |      | 135 | 225   | m $\Omega$       |
| $I_O$                        | Output current                               |   |      |     | 400   | mA               |
| $V_I$                        | 5Vg_ENABLE input-voltage range               |   | -0.5 |     | $V_O$ | V                |
| $V_{IH}$                     | 5Vg_ENABLE threshold high voltage            | $V_{(5Vg)} = 5\text{ V}$  | 2.5  | 3   | 3.5   | V                |
| $V_{IL}$                     | 5Vg_ENABLE threshold low voltage             | $V_{(5Vg)} = 0\text{ V}$  | 1.5  | 2   | 2.5   | V                |
| $V_{(hys)}$                  | Hysteresis voltage                           |   | 0.5  | 1   |       | V                |
| $r_{(pd)}$                   | Internal pulldown resistor                   |   | 300  | 500 | 850   | k $\Omega$       |
| <b>ENABLE</b>                |  |   |      |     |       |                  |
| $V_I$                        | ENABLE input-voltage range                   |   | -0.5 |     | 40    | V                |
| $V_{IH}$                     | ENABLE threshold high voltage                | $8\text{ V} \leq V_{(driver)} \leq 17\text{ V}$   | 2.5  | 3   | 3.5   | V                |
|                              |  | $6\text{ V} \leq V_{(driver)} < 8\text{ V}$   | 1.9  | 3   | 3.5   |                  |
| $V_{IL}$                     | ENABLE threshold low voltage                 | $V_O = 5\text{ V}$  | 1.5  | 2   | 2.5   | V                |
| $V_{(hys)}$                  | Hysteresis voltage                           | $8\text{ V} \leq V_{(driver)} \leq 17\text{ V}$   | 0.5  | 1   |       | V                |
|                              |  | $6\text{ V} \leq V_{(driver)} < 8\text{ V}$   | 0.1  |     |       |                  |

(1) Ensured by characterization.

(2) Tested with inductor having following characteristics:  $L = 33\text{ }\mu\text{H}$ ,  $R_{max} = 0.1\text{ }\Omega$ ,  $I_R = 1.8\text{ A}$ . Output current must be verified in application when inductor  $R_{max}$  (ESR) is increased.

(3) Ensured by characterization. For further details, see [Buck/Boost Transitioning](#).

(4) Ensured by characterization; hysteresis  $15^\circ\text{C}$  (typical)

## Electrical Characteristics (continued)

 $V_{(driver)} = 6\text{ V to }17\text{ V}$ ,  $T_A = -40^\circ\text{C to }125^\circ\text{C}$ , unless otherwise noted

| PARAMETER                              |  | TEST CONDITIONS  | MIN  | TYP  | MAX  | UNIT          |
|--|--|--|------|------|------|---------------|
| <b>RESET</b>                           |  |  |      |      |      |               |
| $V_{(th)}$                             | RESET threshold voltage                |  | 4.51 | 4.65 | 4.79 | V             |
| $V_{(RESET)}$                          | RESET tolerance                        |  |      |      | 3%   |               |
| $t_{(RESET)}$                          | RESET time                             | $C_{(REST)} = 10\text{ nF}$                                    | 8    | 10   | 12   | ms            |
|  |  | $C_{(REST)} = 100\text{ nF}$ , see <sup>(1)</sup>              | 80   | 100  | 120  |               |
| $V_{OL}$                               | RESET output low voltage               | $I_{sink} = 5\text{ mA}$                                       |      |      | 450  | mV            |
|  |  | $I_{sink} = 1\text{ mA}$                                       |      |      | 84   |               |
| $t_{(degitch)}$                        | RESET deglitch time                    | See <sup>(1)</sup>   | 8    | 10   | 12.5 | $\mu\text{s}$ |
| <b>ALARM</b>                           |  |  |      |      |      |               |
| $V_I$                                  | Alarm input-voltage range              |  | -0.5 |      | 40   | V             |
| $V_{IL}$                               | Alarm threshold low voltage            |  | 2.2  | 2.3  | 2.35 | V             |
| $V_{IH}$                               | Alarm threshold high voltage           |  | 2.43 | 2.5  | 2.58 | V             |
| $V_{(hys)}$                            | Hysteresis voltage                     |  |      | 200  |      | mV            |
| $V_{OL}$                               | Alarm output low voltage               | $I_{sink} = 5\text{ mA}$                                       |      |      | 450  | mV            |
|  |  | $I_{sink} = 1\text{ mA}$                                       |      |      | 84   |               |
| <b>LOW-POWER MODE (PULSE MODE) PFM</b> |  |  |      |      |      |               |
| $I_{O(LPM)}$                           | Load current in low-power mode         | $V_{(driver)} < 7\text{ V}$                                    |      |      | 50   | mA            |
| $I_{I(avg)}$                           | Average input current                  | $V_{(driver)} = 11\text{ V}$ , $I_O = 5\text{ mA}$ , CLP = low |      |      | 3.55 | mA            |
| $V_O$                                  | Output-voltage tolerance               | $V_O = 5\text{ V}$   |      | 2.4% | 3%   |               |
| <b>DIGITAL LOW-POWER MODE (CLP)</b>    |  |  |      |      |      |               |
| $V_{IH}$                               | High-level CLP input threshold voltage | Normal mode  | 2.6  |      |      | V             |
| $V_{IL}$                               | Low-level CLP input threshold voltage  | Low-power mode   |      |      | 1.15 | V             |

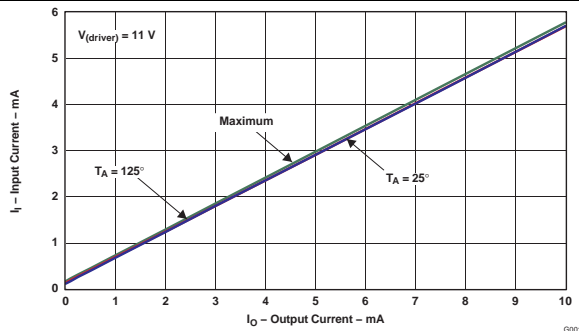
## 6.7 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

| PARAMETER       |                               | TEST CONDITIONS                           | MIN | TYP | MAX | UNIT |
|-----------------|-------------------------------|---|-----|-----|-----|------|
| $f_{(sw)}$      | Switching frequency           | $V_{(Rmod)} = 0\text{ V}$ , modulator OFF |     | 440 |     | kHz  |
| $f_{(sw)ac}$    | Operating-frequency accuracy  | $f_{(sw)} = 440\text{ kHz}$               |     |     | 20% |      |
| $f_{(sw)min}$   | Modulation minimum frequency  |   | 270 | 330 | 445 | kHz  |
| $f_{(sw)max}$   | Modulation maximum frequency  |   | 450 | 550 | 680 | kHz  |
| $f_{(mod)span}$ | Modulation span               |   |     | 220 |     | kHz  |
| $f_{(mod)}$     | Modulation frequency          | $R_{mod} = 12\text{ k}\Omega \pm 1\%$     |     | 28  |     | kHz  |
| $f_{(mod)ac}$   | Modulation-frequency accuracy |   |     |     | 12% |      |

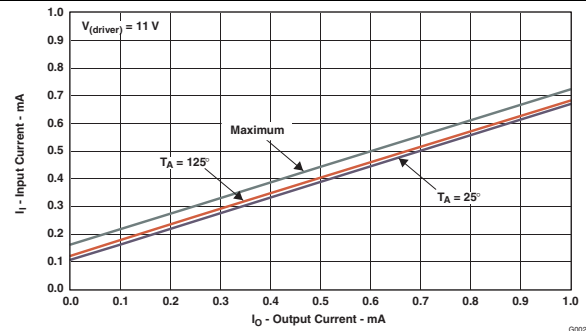
## 6.8 Typical Characteristics

(Reference L1 Terminal, see [Figure 8](#) through [Figure 10](#))



Maximum characteristic specified by design.

Figure 1. Low-Power Mode Current,  $I_O = 0 \text{ mA}–10 \text{ mA}$



Maximum characteristic specified by design.

Figure 2. Low-Power-Mode Current,  $I_O = 0 \text{ mA}–1 \text{ mA}$

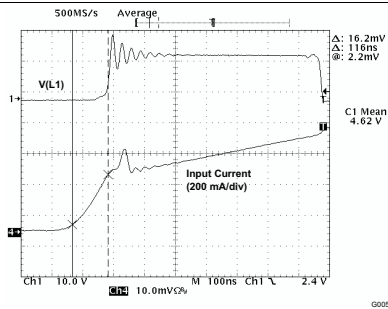


Figure 3. Input Current with Slope Control,  $SCR0 = 0$ ,  $SCR1 = 0$ , Input-Current Slew Rate =  $2.8 \text{ A}/\mu\text{s}$ ,  $I_L = 500 \text{ mA}$ ,  $V_{(driver)} = 15 \text{ V}$

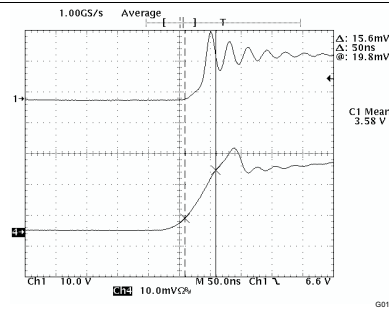


Figure 4. Input Current with Slope Control,  $SCR0 = 1$ ,  $SCR1 = 0$ , Input-Current Slew Rate =  $6.25 \text{ A}/\mu\text{s}$ ,  $I_L = 500 \text{ mA}$ ,  $V_{(driver)} = 15 \text{ V}$

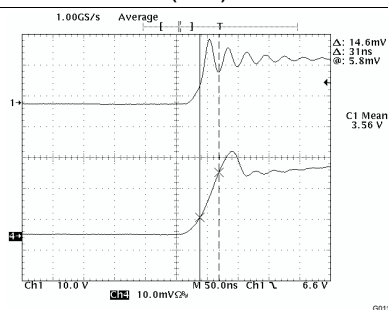


Figure 5. Input Current with Slope Control,  $SCR1 = 1$ ,  $SCR0 = 0$ , Input-Current Slew Rate =  $9.4 \text{ A}/\mu\text{s}$ ,  $I_L = 500 \text{ mA}$ ,  $V_{(driver)} = 15 \text{ V}$

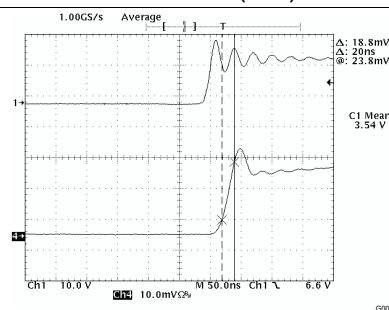


Figure 6. Input Current With Slope Control,  $SCR0 = 1$ ,  $SCR1 = 1$ , Input-Current Slew Rate =  $18.8 \text{ A}/\mu\text{s}$ ,  $I_L = 500 \text{ mA}$ ,  $V_{(driver)} = 15 \text{ V}$



Typical Characteristics (continued)

(Reference L1 Terminal, see Figure 8 through Figure 10)

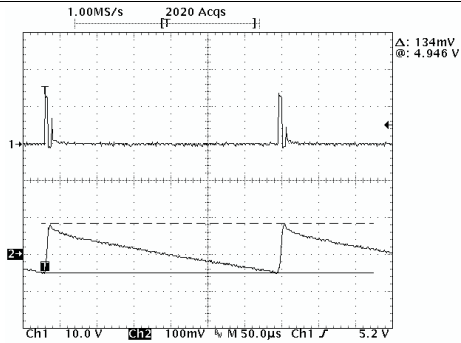


Figure 7. Low-Power-Mode Operation,  $I_L = 15 \text{ mA}$ ,  $C_O = 47 \mu\text{F}$

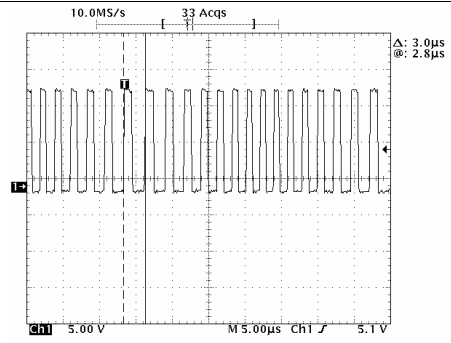


Figure 8. Minimum Switching Frequency (333 kHz) with Modulation Enabled,  $R_{\text{mod}} = 12 \text{ k}\Omega$ ,  $I_L = 200 \text{ mA}$

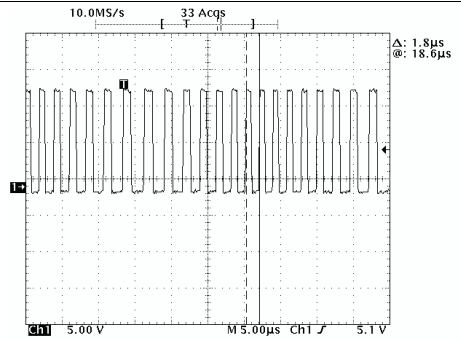


Figure 9. Maximum Switching Frequency (555 kHz) With Modulation Enabled,  $R_{\text{mod}} = 12 \text{ k}\Omega$ ,  $I_L = 200 \text{ mA}$

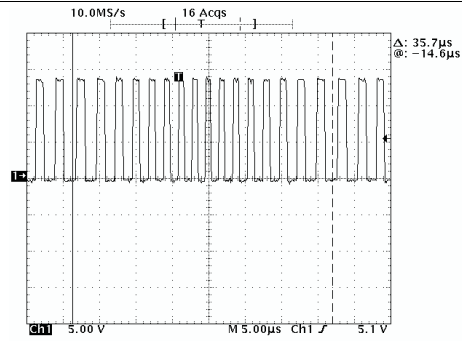


Figure 10. Modulation Frequency (Full Span) of 28 kHz

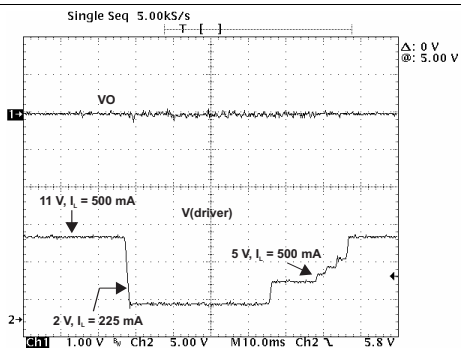


Figure 11. Input Voltage Excursions (Similar to Low-Crank Conditions)

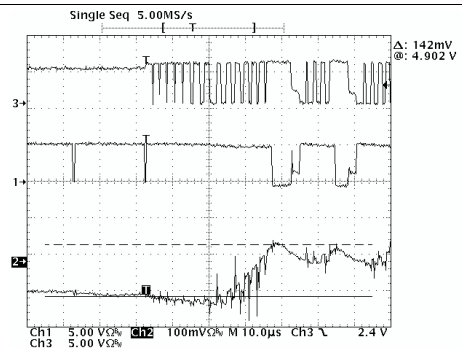
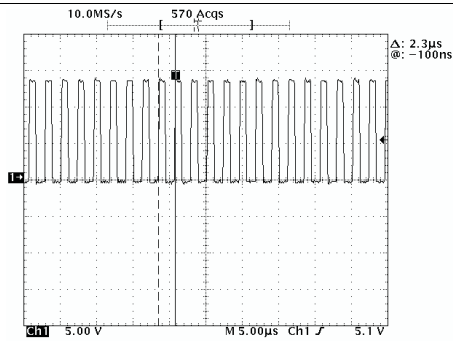


Figure 12. Switched-Mode Regulator Transition from Buck Mode to Boost Mode,  $I_L = 400 \text{ mA}$

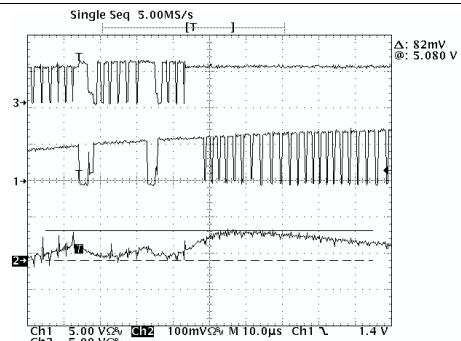
Typical Characteristics (continued)

(Reference L1 Terminal, see Figure 8 through Figure 10)



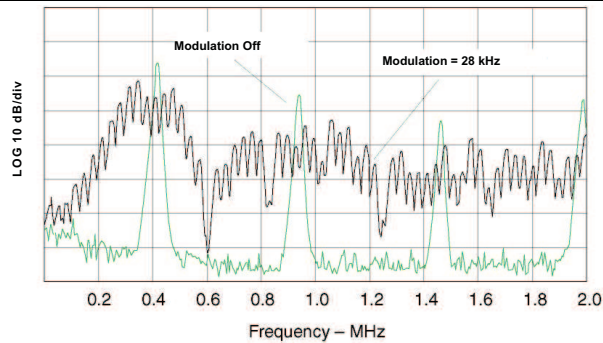
G012

Figure 13. Nominal Switching Frequency of Q1 Switch (446 kHz) With Modulation Function Disabled,  $I_L = 200$  mA



G016

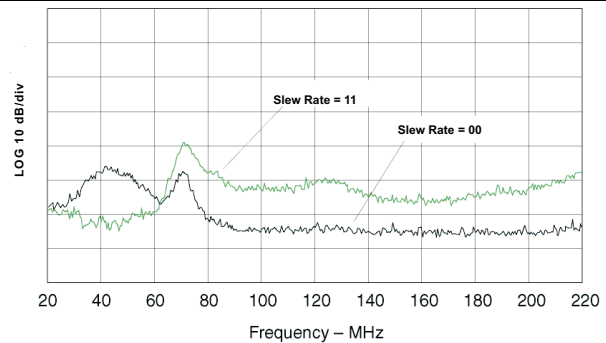
Figure 14. Switched-Mode Regulator Transition from Boost Mode to Buck Mode,  $I_L = 400$  mA



G017

These values represent conducted EMI results of a test board for display purposes only. Actual results may vary greatly depending on board layout and external components and must be verified in actual application.

Figure 15. Conducted Emissions on Test Board Showing Effects of Switching-Frequency Modulation



G018

These values represent conducted EMI results of a test board for display purposes only. Actual results may vary greatly depending on board layout and external components and must be verified in actual application.

Figure 16. Conducted Emissions on Test Board Showing Effects of Minimum and Maximum Slew Rate Settings

## 7 Detailed Description

### 7.1 Overview

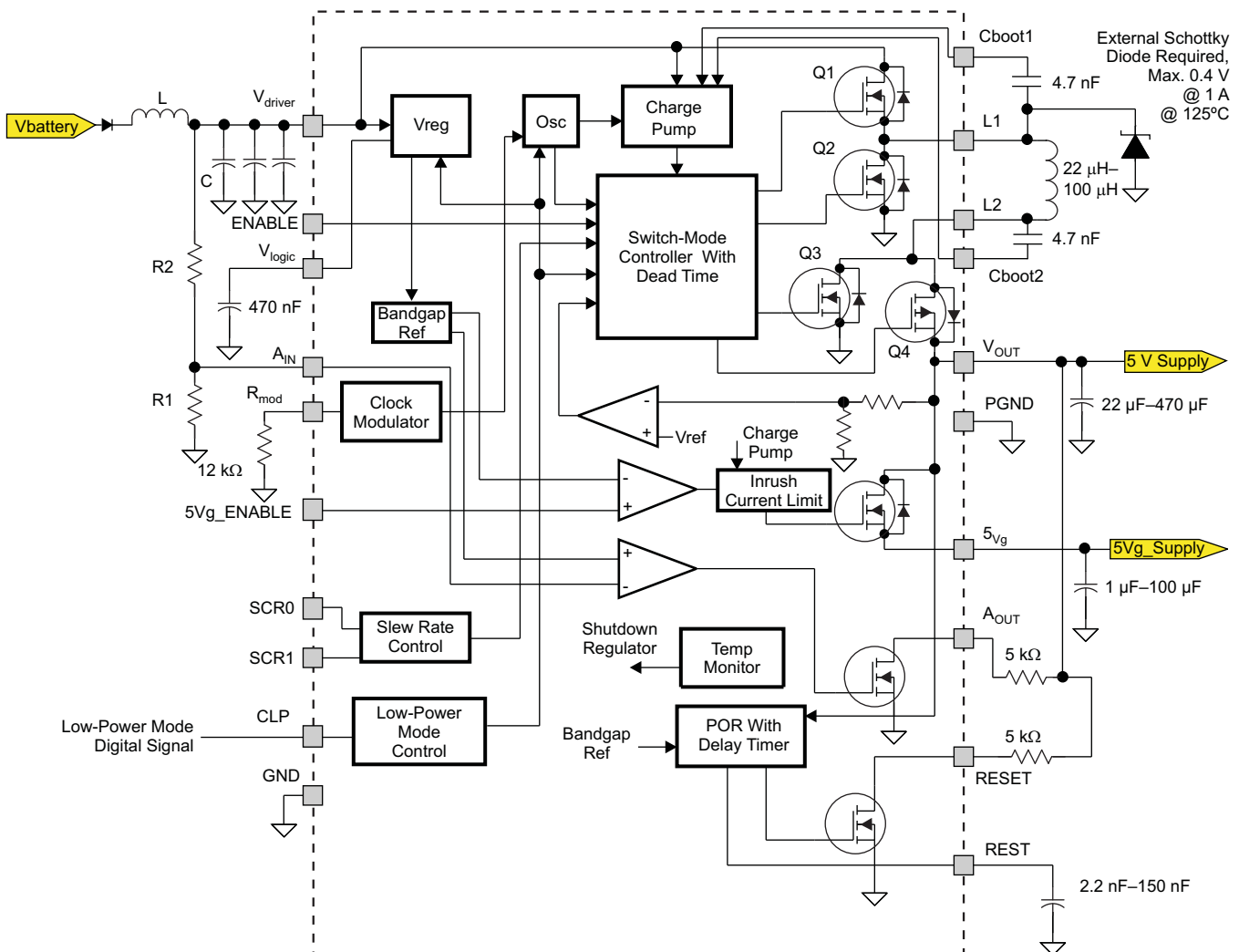
The TPS55065 is a buck/boost switched-mode regulator that operates in a power-supply concept to ensure a stable output voltage with input voltage excursions and specified load range.

The device provides an alarm indicator and reset output to interface with systems that require supervisory function.

The switching regulator offers a clock modulator and a current-mode slew-rate control for the internal switching transistor (Q1) to minimize EMI.

An internal low- $r_{DS(on)}$  switch has a current-limit feature to prevent inadvertent reset when turning on the 5-V<sub>g</sub> output.

### 7.2 Functional Block Diagram



B0130-01

All component values are typical.

## 7.3 Feature Description

### 7.3.1 Switched-Mode Input/Output Terminals (L1, L2)

The external inductor for the switched-mode regulator is connected between terminals L1 and L2. This inductor is placed close to the terminals to minimize parasitic effects. For stability, use an inductor with 20  $\mu\text{H}$  to 100  $\mu\text{H}$ .

### 7.3.2 Supply Terminal ( $V_{\text{driver}}$ )

The input voltage of the device is connected to the  $V_{\text{driver}}$  terminal. This input line requires a filter capacitor to minimize noise. TI recommends using a low-ESR aluminum or tantalum input capacitor. The relevant parameters for the input capacitor are the voltage rating and RMS current rating. The voltage rating should be approximately 1.5 times the maximum applied voltage for an aluminum capacitor and 2 times for a tantalum capacitor. In buck mode, the RMS current is  $I_{\text{OUT}} \times \sqrt{D - D^2}$ , where D is the duty cycle and its maximum RMS current value is reached when  $D = 50\%$  with  $I_{\text{RMS}} = I_{\text{OUT}}/2$ . In boost mode, the RMS current is  $0.3 \times \Delta I$ , where  $\Delta I$  is the peak-to-peak ripple current in the inductor. To achieve this, ESR ceramic capacitors are used in parallel with the aluminum or tantalum capacitors.

### 7.3.3 Internal Supply Decoupling Terminal ( $V_{\text{logic}}$ )

The  $V_{\text{logic}}$  terminal is used to decouple the internal power-supply noise by use of a 470-nF capacitor. This terminal can also be used as an output supply for the logic-level inputs for this device (SCR0, SCR1, ENABLE, CLP, and 5Vg\_ENABLE).

### 7.3.4 Input Voltage Monitoring Terminal ( $A_{\text{IN}}$ )

The  $A_{\text{IN}}$  terminal is used to program the threshold voltage for monitoring and detecting undervoltage conditions on the input supply. A maximum of 40 V may be applied to this terminal and the voltage at this terminal may exceed the  $V_{\text{driver}}$  input voltage without effecting the device operation. The resistor divider network is programmed to set the undervoltage detection threshold on this terminal (see the application schematic). The input has a typical hysteresis of 200 mV with a typical upper limit threshold of 2.5 V and a typical lower limit threshold of 2.3 V. When  $V_{\text{AIN}}$  falls below 2.3 V,  $V_{\text{AOUT}}$  is asserted low; when  $V_{\text{AIN}}$  exceeds 2.5 V,  $V_{\text{AOUT}}$  is in the high-impedance state.

The equations to set the upper and lower thresholds of  $V_{\text{AIN}}$  are:

Upper:

$$V_{\text{driver}} = 2.5 \text{ V} \times \frac{R1 + R2}{R1}$$

Lower:

$$V_{\text{driver}} = 2.3 \text{ V} \times \frac{R1 + R2}{R1}$$

(1)

### 7.3.5 Input Undervoltage Alarm Terminal ( $A_{\text{OUT}}$ )

The  $A_{\text{OUT}}$  terminal is an open-drain output that asserts low when the input voltage falls below the set threshold on the  $A_{\text{IN}}$  input.

### 7.3.6 Reset Delay Timer Terminal (REST)

The REST terminal sets the desired delay time to assert the RESET terminal low after the 5-V supply has exceeded 4.65 V (typical). The delay can be programmed in the range of 2.2 ms to 150 ms using capacitors in the range of 2.2 nF to 150 nF. The delay time is calculated using [Equation 2](#):

$$\text{RESET delay} = C_{\text{(REST)}} \times 1 \text{ ms}$$

where  $C_{\text{(REST)}}$  has nF units.

(2)

### 7.3.7 Reset Terminal (RESET)

The RESET terminal is an open-drain output. The power-on reset output is asserted low until the output voltage exceeds the 4.65-V threshold and the reset delay timer has expired. Additionally, whenever the ENABLE terminal is low, RESET is immediately asserted low regardless of the output voltage.

## Feature Description (continued)

### 7.3.8 Main Regulator Output Terminal ( $V_{OUT}$ )

The  $V_{OUT}$  terminal is the output of the switched-mode regulated supply. This terminal requires a filter capacitor with low-ESR characteristics to minimize output ripple voltage. For stability, a capacitor with 22  $\mu\text{F}$  to 470  $\mu\text{F}$  should be used. The total capacitance at pin  $V_{OUT}$  and pin 5Vg must be less than or equal to 470  $\mu\text{F}$ .

### 7.3.9 Low-Power-Mode Terminal (CLP)

The CLP terminal controls the low-power mode of the device. An external low digital signal switches the device to low-power mode or normal mode when the input is high.

### 7.3.10 Switch-Output Terminal (5Vg)

The 5Vg terminal switches the 5-V regulated output. The output voltage of the regulator can be enabled or disabled using this low- $r_{DS(on)}$  internal switch. This switch has a current-limiting function to prevent generation of a reset signal at turnon caused by the capacitive load on the output or overload condition. When the switch is enabled, the regulated output may deviate and drop momentarily to a tolerance of 7% until the 5Vg capacitor is fully charged. This deviation depends on the characteristics of the capacitors on  $V_{OUT}$  and 5Vg.

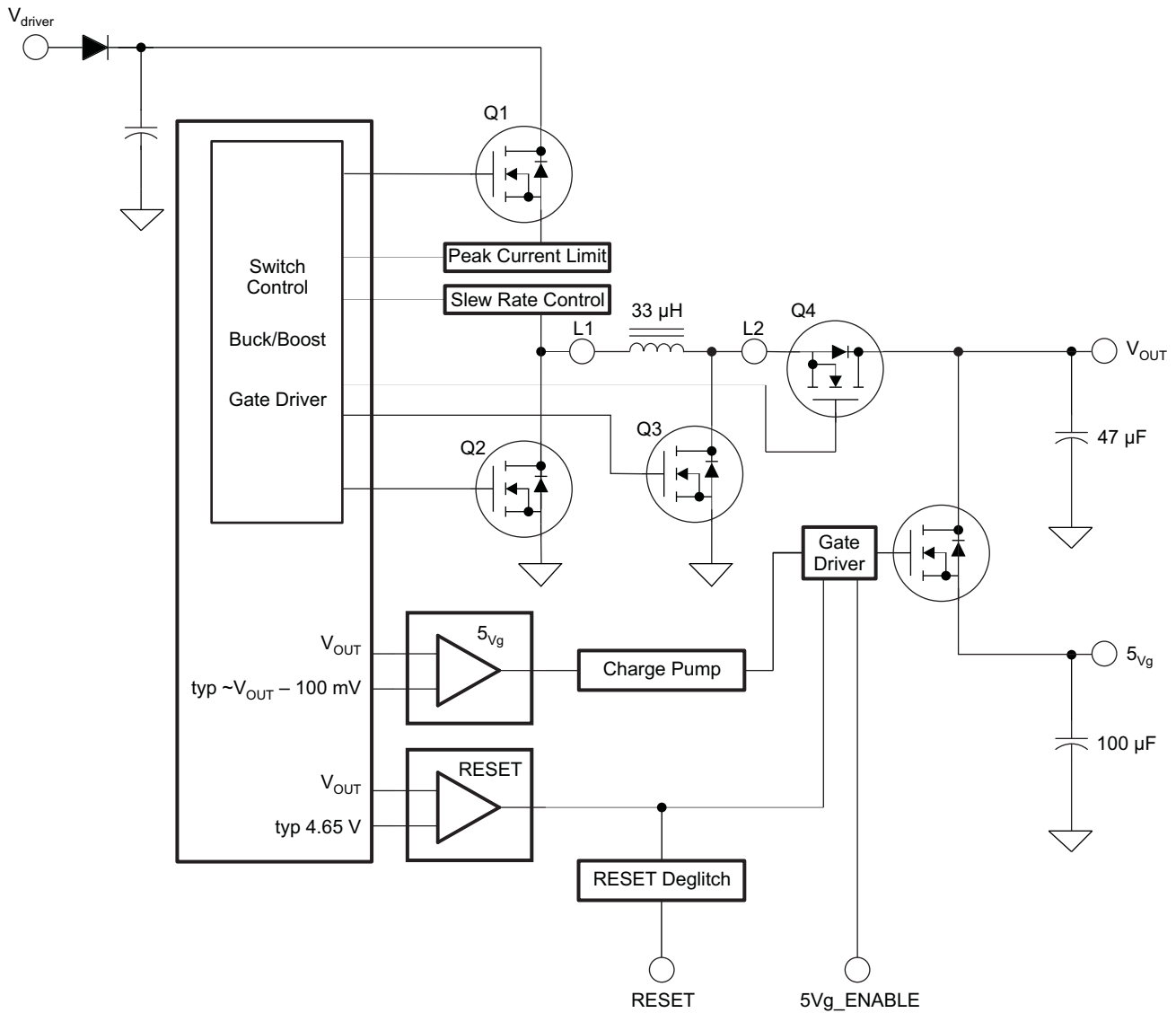
### 7.3.11 5Vg-Enable Terminal (5Vg\_ENABLE)

The 5Vg\_ENABLE is a logic-level input for enabling the switch output on 5Vg.

For the functional terminal, see 5Vg\_ENABLE results in [Table 1](#):

**Table 1. 5Vg\_ENABLE Function**

| 5Vg_ENABLE                                 | Function   |
|--|------------|
| 0  | 5Vg is off |
| Open (internal pulldown = 500 k $\Omega$ ) | 5Vg is off |
| 1  | 5Vg is on  |



S0174-01

Figure 17. Current-Limit Switched Output 5Vg

7.3.12 Slew-Rate Control Terminals (SCR0, SCR1)

The slew rate of the switching transistor Q1 is set using the SCR0 and SCR1 terminals.

Table 2 shows the values of the slew rate (SR):

Table 2. SR Values

| SCR1 | SCR0 | SR <sub>Q1</sub> |
|------|------|------------------|
| 0    | 0    | Slow             |
| 0    | 1    | Medium-slow      |
| 1    | 0    | Medium-fast      |
| 1    | 1    | Fast             |

See the converter efficiency plots in the *Typical Characteristics* section to determine power dissipation.

### 7.3.13 Modulator Frequency Setting (Terminal R<sub>mod</sub>)

The R<sub>mod</sub> terminal adjusts the clock modulator frequency. A resistor of R<sub>mod</sub> = 12 kΩ generates a modulation frequency of 28 kHz. The modulator function may be disabled by connecting R<sub>mod</sub> to GND and the device operates with the nominal frequency. The modulator function cannot be activated during IC operation, only at IC start-up.

### 7.3.14 Ground Terminal (PGND)

The PGND terminal is the power ground for the device.

### 7.3.15 Enable Terminal (ENABLE)

The ENABLE terminal allows the enabling and disabling of the switch mode regulator. A maximum of 40 V may be applied to this terminal to enable the device and increasing it above the V<sub>(driver)</sub> input voltage does not affect the device operation.

The functionality of the ENABLE terminal is described in [Table 3](#):

**Table 3. ENABLE Function**

| ENABLE | Function    |
|--------|-------------|
| 0      | Vreg is off |
| Open   | Undefined   |
| 1      | Vreg is on  |

### 7.3.16 Bootstrap Terminals (CBOOT1 and CBOOT2)

An external bootstrap capacitor is required for driving the internal high-side MOSFET switch. A 4.7-nF ceramic capacitor is typically required.

## 7.4 Device Functional Modes

### 7.4.1 Clock Modulator

To minimize EMI issues associated with the switched-mode regulator, the device offers an integrated clock modulator. The function of the clock modulator is to modulate the switching frequency and to distribute the energy over the wave band.

The average switching frequency is 440 kHz (typical) and varies between 330 kHz and 550 kHz at a rate set by the R<sub>mod</sub> resistor. A typical value of 12 kΩ on the R<sub>mod</sub> terminal relates to a 28-kHz modulation frequency. The clock modulator function can only be activated during IC start-up, not during IC operation.

The equation for the modulation frequency is as follows:

$$f_{(\text{mod})} \text{ (Hz)} = (-2.2 \times R_{\text{mod}}) + 54.5 \text{ kHz}$$

when R<sub>mod</sub> = 8 kΩ to 16 kΩ. (3)

### 7.4.2 Buck/Boost Transitioning

The operation mode switches automatically between buck and boost modes depending on the input voltage of V<sub>(driver)</sub> and output load conditions. During start up, when V<sub>(driver)</sub> is less than 5.8 V (typical), the device starts in boost mode and continues to run in boost mode until V<sub>(driver)</sub> exceeds 5.8 V; at which time, the device switches over to buck mode. In buck mode, the device continues to run in buck mode until it is required to switch back to boost to hold regulation. This crossover window to switch to boost mode is when V<sub>(driver)</sub> is between 5.8 V and 5 V and depends on the loading conditions. When V<sub>driver</sub> drops below 5.8 V but the device is holding regulation (~2%), the device remains in buck mode. However, when V<sub>(driver)</sub> is within the 5.8-V to 5-V window and V<sub>OUT</sub> drops to 4.9 V, the device crosses over to boost mode to hold regulation. In boost mode, the device remains in

## Device Functional Modes (continued)

boost mode until  $V_{(driver)}$  exceeds 5.8 V; at which time, the device enters the buck mode. When the device is operating in boost mode and  $V_{(driver)}$  is in the crossover window of 5.8 V to 5 V, the output regulation may contain a higher than normal ripple and only maintain a 3% tolerance. This ripple and tolerance depends on the loading and improves with a higher loading condition. When the device is operated with low-power mode active (CLP = low) and high output currents (>50 mA), the buck/boost transitioning can cause a reset signal at the RESET pin.

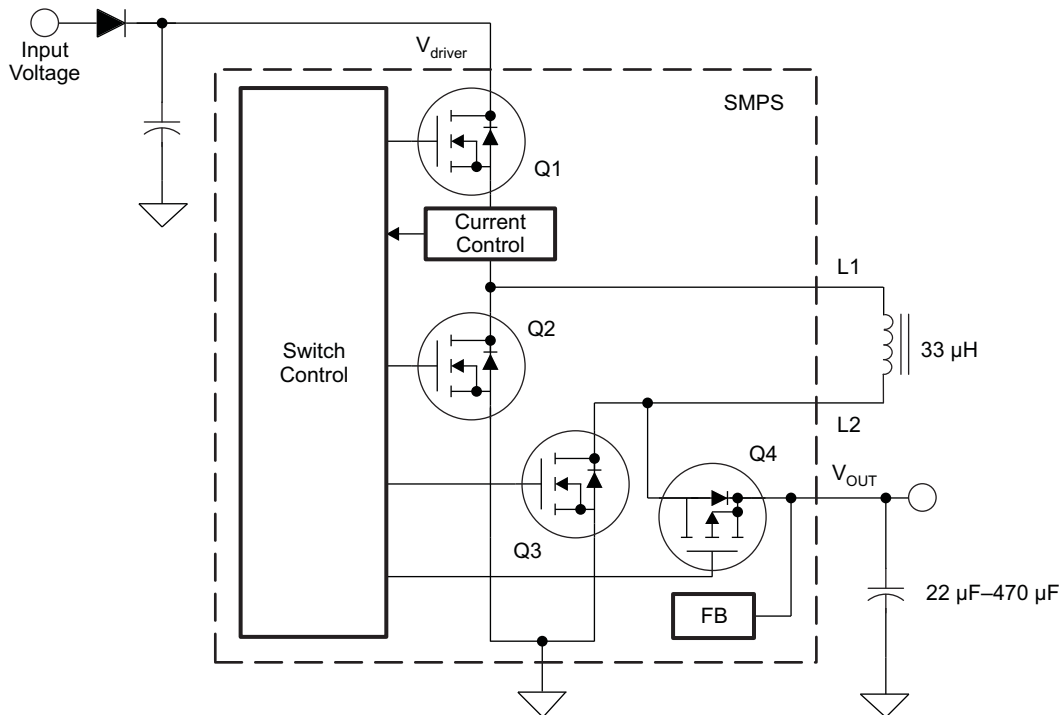
### 7.4.3 Buck SMPS

In buck mode, the duty cycle of transistor Q1 sets the voltage  $V_{OUT}$ . The duty cycle of transistor Q1 varies 10% to 99% depending on the input voltage,  $V_{(driver)}$ . If the peak inductor current (measured by Q1) exceeds 450 mA (typical), Q2 is turned on for this cycle (synchronized rectification). Otherwise, the current recirculates through Q2 as a free-wheeling diode. The detection for synchronous or asynchronous mode is done cycle-by-cycle.

To avoid a cross-conduction current between Q1 and Q2, an inherent delay is incorporated when switching Q1 off and Q2 on and vice versa.

In buck mode, transistor Q3 is not required and is switched off. Transistor Q4 is switched on to reduce power dissipation.

The switch timings for transistors Q3 and Q4 are not considered. In buck mode, the logical control of the transistors does not change.



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**Figure 18. Buck/Boost Switch Mode Configuration**

### 7.4.4 Boost SMPS

In boost mode, the duty cycle of transistor Q3 controls the output voltage  $V_{OUT}$ . The duty cycle is internally adjusted 5% to 85% depending on the internally sensed voltage of the output. Synchronized rectification occurs when  $V_{(driver)}$  is below 5 V.

To avoid a discharging of the buffer capacitor, a simultaneous switching on of Q3 and Q4 is not allowed. An inherent delay is incorporated between Q3 switching off and Q4 switching on and vice versa.

In boost mode, transistor Q2 is not required and remains off. Transistor Q1 is switched on for the duration of the boost-mode operation (serves as a supply line).



## Device Functional Modes (continued)

The switch timings of transistors Q1 and Q2 are not considered. In boost mode, the logical control of the transistors does not change.

### 7.4.5 Extension of the Input Voltage Range on $V_{(driver)}$

To ensure a stable 5-V output voltage with the output load in the specified range, the  $V_{(driver)}$  supply must be greater than or equal to 5 V for greater than 1 ms (typical). After a period of 1 ms (typical), the logic may be supplied by the  $V_{OUT}$  regulator and the  $V_{(driver)}$  supply may be capable of operating down to 1.5 V.

The switched-mode regulator does not start at  $V_{(driver)}$  less than 5 V.

### 7.4.6 Low-Power Mode

To reduce quiescent current and to provide efficient operation, the regulator enters a pulsed mode.

The device enters this mode by a logic-level low on this terminal.

Automatic low-power mode is not available. The low-power-mode function is not available in boost mode. The device leaves low-power mode during boost mode regardless of the logic level on the CLP terminal.

### 7.4.7 Temperature and Short-Circuit Protection

To prevent thermal destruction, the device offers overtemperature protection to disable the IC. Also, short-circuit protection is included for added protection on  $V_{OUT}$  and 5Vg.

### 7.4.8 Switch Output Terminal (5Vg) Current Limitation

A charge pump drives the internal FET, which switches the primary output voltage  $V_{OUT}$  to the 5Vg pin. Protection is implemented to prevent the output voltage from dropping below its specified value while enabling the secondary output voltage. An explanation of the block diagram (see Figure 1) is given by the following example:

- Device is enabled, output voltage  $V_{OUT}$  is up and stable.
- 5Vg is enabled (pin 5Vg\_ENABLE set to high) with load resistance connected to 5Vg pin.
- If output voltage  $V_{OUT}$  drops below typical ( $V_{OUT} - 100$  mV), the charge pump of the 5Vg FET is switched off and the FET remains on for a while as the gate voltage drops slowly.
- If  $V_{OUT}$  drops below the RESET threshold of 4.65 V (typical), the FET of the secondary output voltage 5Vg is switched off (gate drawn to ground level).
- A deglitch time ensures that a device reset does not occur if  $V_{OUT}$  drops to the reset level during the 5Vg turnon phase.
- If  $V_{OUT}$  rises above typical ( $V_{OUT} - 100$  mV), the charge pump of the 5Vg FET is switched on and drives the gate of the 5Vg FET on.

### 7.4.9 Soft Start

On power up, the device offers a soft-start feature which ramps the output of the regulator at a slew of 10 V/ms. When a reset occurs, the soft start is reenabled. Additionally, if the output capacitor is greater than 220  $\mu$ F (typical), the slew rate decreases to a value set by the internal current limit. In boost mode, the soft-start feature is not active.

## 8 Application and Implementation

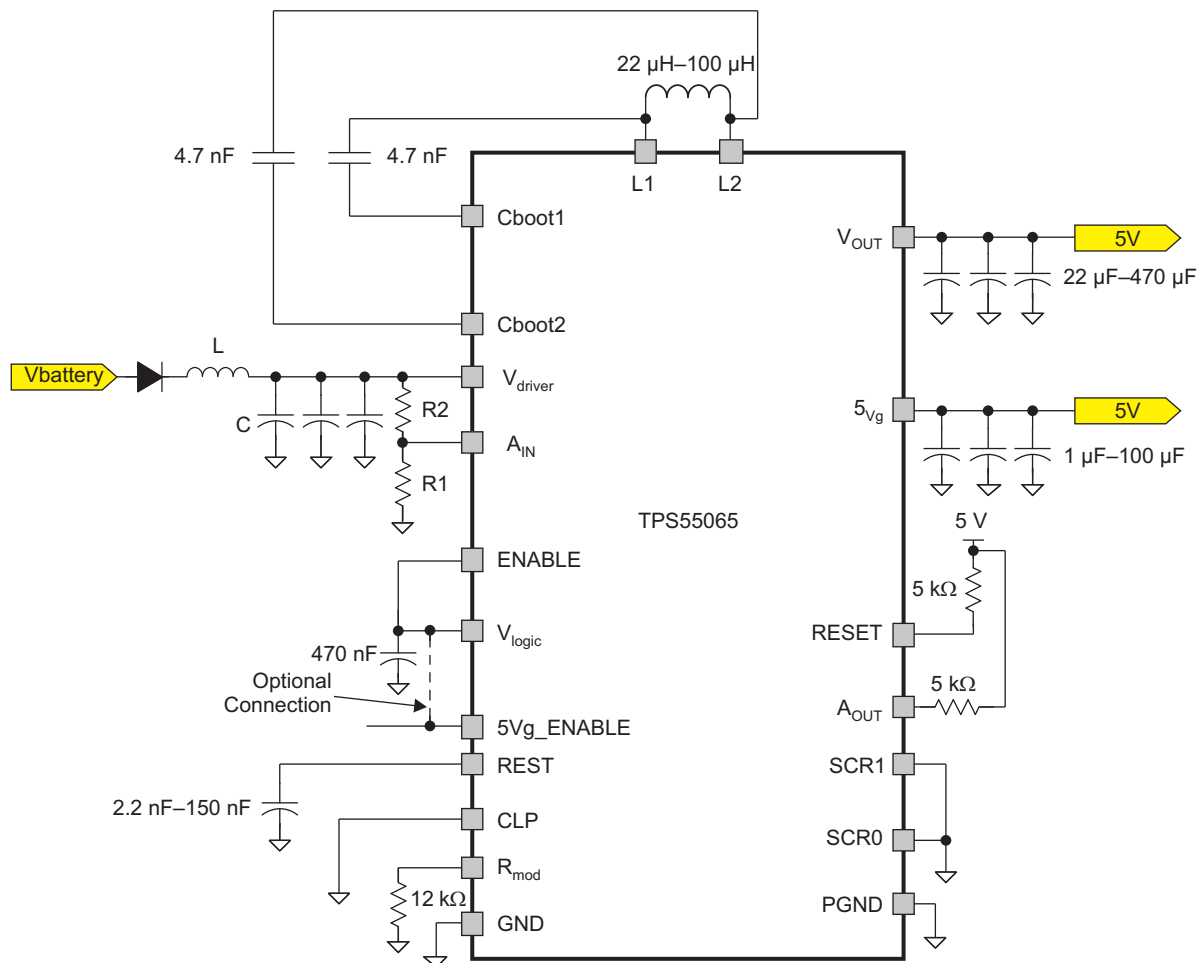
### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### 8.1 Application Information

The TPS55065 can be operated in a buck boost configuration with voltage mode control. The device is capable of monitoring the output as well as the input supply rail. The device also offers a frequency modulation scheme for minimizing EMI. The slew rate is set using the SCR0 and the SCR1 terminals. The average converter efficiency varies with the different slew rate controls of the Q1 switching FET. These variations are demonstrated using this design example at an input voltage of 11 V and 17 V.

### 8.2 Typical Application



S0183-01

- To minimize voltage ripple on the output due to transients, it is recommended to use a low-ESR capacitor on the  $V_{OUT}$  line.
- The L and C component values are system application dependent for EMI consideration.

**Figure 19. Application Schematic**

## Typical Application (continued)

### NOTE

When this attachment method is not implemented correctly, this product may operate inefficiently. Power dissipation capability may be adversely affected when the device is incorrectly mounted onto the circuit board.

### 8.2.1 Design Requirements

For this design example, use the parameters listed in [Table 4](#) as the input parameters.

**Table 4. Design Parameters**

| DESIGN PARAMETERS        | VALUE        |
|--------------------------|--------------|
| Input voltage V(driver)  | 11 V to 18 V |
| Output current (maximum) | 500 mA       |

Four different SCRx settings will be used to analyze the difference in converter efficiency with variations in slew rate (see [Figure 20](#)). The Buck equations mentioned in [Buck Mode](#) will be used to calculate the rest of the design parameters.

### 8.2.2 Detailed Design Procedure

#### 8.2.2.1 Buck Mode

- Select inductor ripple current  $\Delta I_L$ : for example,  $\Delta I_L = 0.2 \times I_{OUT}$
- Calculate inductor L

$$L = \frac{(V_{IN} - V_{OUT}) \times V_{OUT}}{f_{SW} \times \Delta I_L \times V_{IN}} \quad (\text{H})$$

where  $f_{SW}$  is the regulator switching frequency.

(4)

- Inductor peak current

$$I_{L,max} = I_{OUT} + \frac{\Delta I_L}{2} \quad (\text{A})$$

(5)

- Output voltage ripple

$$\Delta V_{OUT} = \Delta I_L \times \left( \text{ESR} + \frac{1}{8 \times f_{SW} \times C_{OUT}} \right) (V_{(p-p)})$$

(6)

Usually, the first term is dominant.

$$C_{OUT} = \frac{I_{pk} (t_{ON} + t_{OFF})}{8 \times V_{ripple}} \quad (\text{F})$$

(7)

Using the previous equations, with  $V_{in}$  (maximum) as 18 V,  $V_{out}$  as 5 V,  $f_{SW}$  as 440 kHz, and Inductor ripple current of 0.1 A, the inductance is calculated to be 82.1  $\mu\text{H}$  with inductor peak current as 0.55 A.

#### 8.2.2.2 Boost Mode

- Select inductor ripple current  $\Delta I_L$ : for example  $\Delta I_L = 0.2 \times I_{IN}$
- Calculate inductor L

$$L = \frac{(V_{OUT} - V_{IN}) \times V_{IN}}{f_{SW} \times \Delta I_L \times V_{OUT}} \quad (\text{H})$$

where  $f_{SW}$  is the regulator switching frequency.

(8)

- Inductor peak current

$$I_P = I_{L,max} = I_{IN} + \frac{\Delta I_L}{2} \quad (\text{A})$$

(9)

- Output voltage ripple

$$\Delta V_{OUT} = I_P \times ESR + \frac{I_{OUT} \times \left(1 - \frac{V_{IN}}{V_{OUT}}\right)}{f_{SW} \times C_{OUT}} \left(V_{(p-p)}\right) \tag{10}$$

### 8.2.3 Application Curve

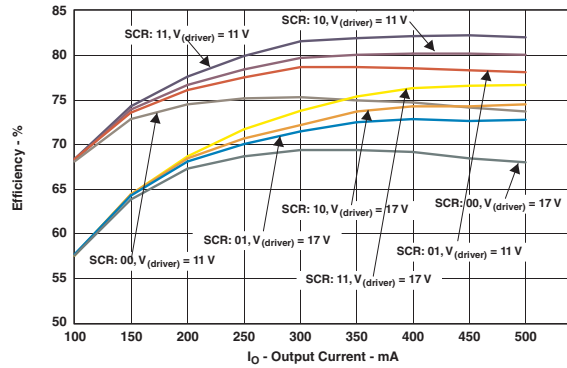


Figure 20. Converter Efficiency

## 9 Power Supply Recommendations

The TPS55065-Q1 device is designed to operate from an input voltage up to 40 V. Ensure that the input supply is well regulated. Furthermore, if the supply voltage in the application is likely to reach negative voltage (for example, reverse battery), a forward diode must be placed at the input of the supply. For the V<sub>IN</sub> pin, a good quality ceramic capacitor is recommended. Capacitance de-rating for aging, temperature, and DC bias must be taken into account while determining the capacitor value. The decoupling capacitor must be as close as possible to the Input pin for proper filtering. The use of a low-ESR capacitor at the V<sub>OUT</sub> line is recommended to minimize the voltage ripple on the output due to transients. The L and C component values can be chosen as per specifications.

## 10 Layout

### 10.1 Layout Guidelines

The following guidelines are recommended for PCB layout of the TPS55065 device.

#### 10.1.1 Inductor

Use a low-EMI inductor with a ferrite-type closed core. Other types of inductors may be used; however, they must have low-EMI characteristics and be located away from the low-power traces and components in the circuit.

#### 10.1.2 Filter Capacitors

Input ceramic filter capacitors should be located in the close proximity of the V<sub>driver</sub> terminal. Surface-mount capacitors are recommended to minimize lead length and reduce noise coupling.

#### 10.1.3 Traces and Ground Plane

All power (high-current) traces should be thick and as short as possible. The inductor and output capacitors should be as close to each other as possible. This reduces EMI radiated by the power traces due to high switching currents.

In a two-sided PCB, it is recommended to have ground planes on both sides of the PCB to help reduce noise and ground-loop errors. The ground connection for the input and output capacitors and IC ground should be connected to this ground plane.

## Layout Guidelines (continued)

In a multilayer PCB, the ground plane is used to separate the power plane (where high switching currents and components are placed) from the signal plane (where the feedback trace and components are) for improved performance.

Also, arrange the components such that the switching-current loops curl in the same direction. Place the high-current components such that during conduction, the current path is in the same direction. This prevents magnetic field reversal caused by the traces between the two half-cycles, helping to reduce radiated EMI.

## 10.2 Layout Example

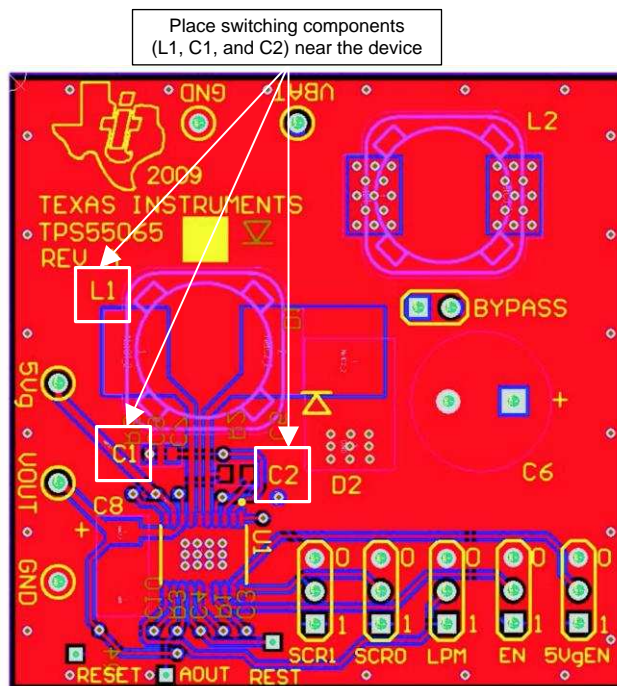
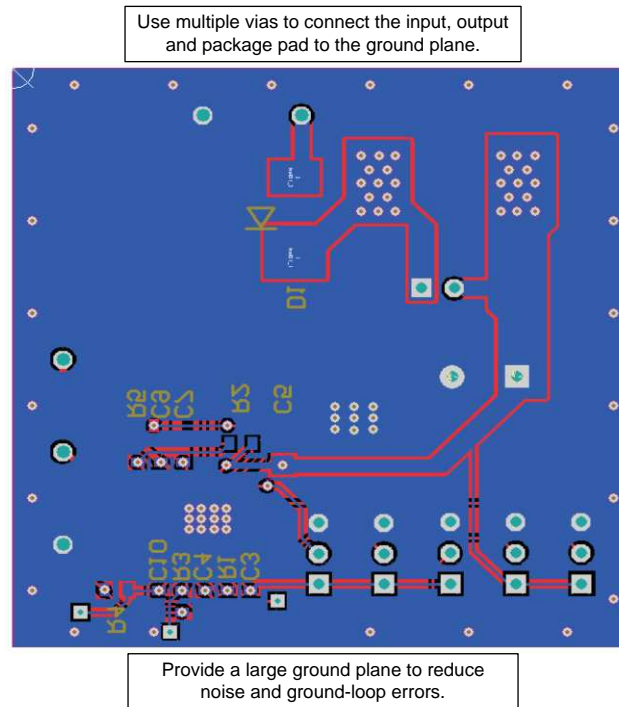


Figure 21. Top Layer

**Layout Example (continued)**



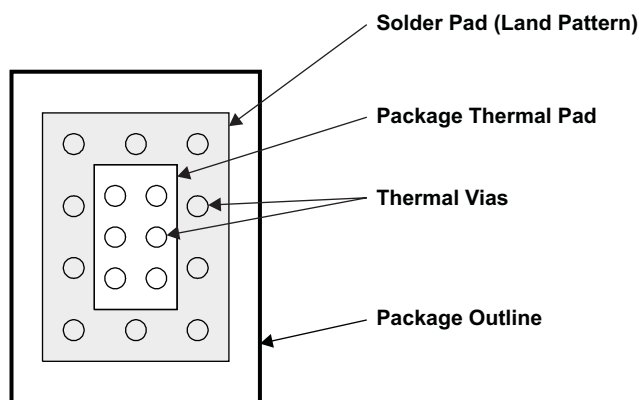
**Figure 22. Bottom Layer**

To maximize the efficiency of this package for application on a single-layer or multilayer PCB, certain guidelines must be followed when laying out this device on the PCB.

The following information is to be used as a guideline only.

For further information see the *PowerPAD Thermally Enhanced Package* technical brief (SLMA002).

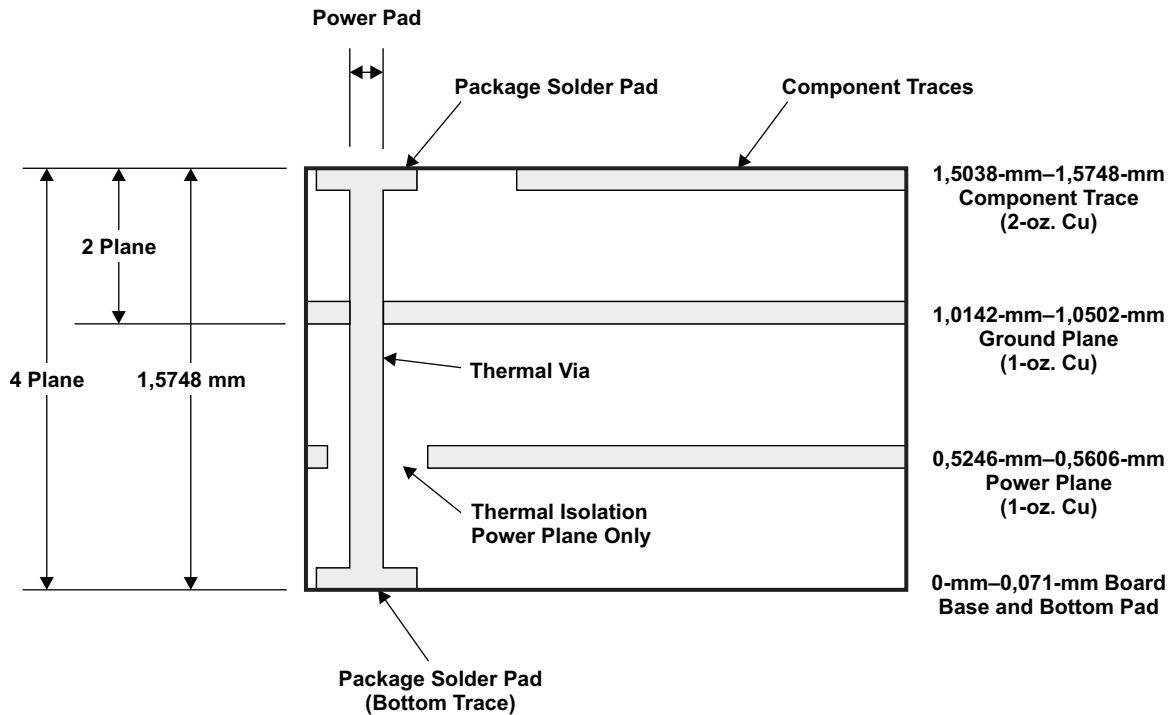
The following are guidelines for mounting the PowerPAD™ IC on a multilayer PCB with a ground plane.



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**Figure 23. Package and PCB Land Configuration for a Multilayer PCB**

Layout Example (continued)

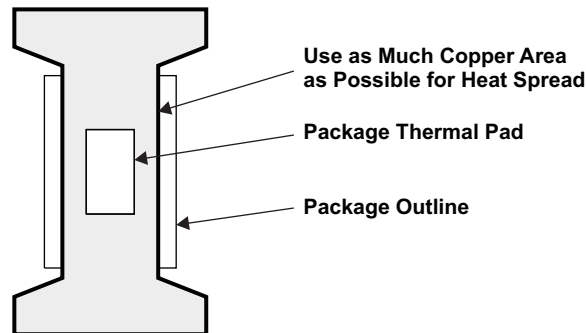


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Figure 24. Multilayer Board (Side View)

In a multilayer board application, the thermal vias are the primary method of heat transfer from the package thermal pad to the internal ground plane.

The efficiency of this method depends on several factors (die area, number of thermal vias, thickness of copper, and so forth). See the *PowerPAD Thermally Enhanced Package* technical brief ([SLMA002](#)).



M0028-01

Figure 25. Land Configuration for Single-Layer PCB

Layout recommendation is to use as much copper area for the power-management section of a single-layer board as possible. In a single-layer board application, the thermal pad is attached to a heat spreader (copper areas) by using a low-thermal-impedance attachment method (solder paste or thermal-conductive epoxy). In both of these cases, it is advisable to use as much copper and as many traces as possible to dissipate the heat.

## 11 Device and Documentation Support

### 11.1 Documentation Support

#### 11.1.1 Related Documentation

For related documentation see the following:

- *PowerPAD Thermally Enhanced Package*, [SLMA002](#)

### 11.2 Trademarks

PowerPAD is a trademark of Texas Instruments.

All other trademarks are the property of their respective owners.

### 11.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### 11.4 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



**PACKAGING INFORMATION**

| Orderable Device | Status<br>(1) | Package Type | Package Drawing | Pins | Package Qty | Eco Plan<br>(2) | Lead finish/<br>Ball material<br>(6) | MSL Peak Temp<br>(3) | Op Temp (°C) | Device Marking<br>(4/5) | Samples |
|------------------|---------------|--------------|-----------------|------|-------------|-----------------|--------------------------------------|----------------------|--------------|-------------------------|---------|
| TPS55065QPWRQ1   | ACTIVE        | HTSSOP       | PWP             | 20   | 2000        | RoHS & Green    | NIPDAU                               | Level-2-260C-1 YEAR  | -40 to 125   | 55065Q                  | Samples |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "-" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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**TAPE AND REEL INFORMATION**

**QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**


\*All dimensions are nominal

| Device          | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-----------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| TPS55065QPWPRQ1 | HTSSOP       | PWP             | 20   | 2000 | 330.0              | 16.4               | 6.95    | 7.1     | 1.6     | 8.0     | 16.0   | Q1            |

**TAPE AND REEL BOX DIMENSIONS**


\*All dimensions are nominal

| Device          | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|-----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| TPS55065QPWPRQ1 | HTSSOP       | PWP             | 20   | 2000 | 350.0       | 350.0      | 43.0        |

# MECHANICAL DATA

PWP (R-PDSO-G20)

PowerPAD™ PLASTIC SMALL OUTLINE



4073225-4/1 05/11

- NOTES:
- All linear dimensions are in millimeters.
  - This drawing is subject to change without notice.
  - Body dimensions do not include mold flash or protrusions. Mold flash and protrusion shall not exceed 0.15 per side.
  - This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.
  - Falls within JEDEC MO-153

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# THERMAL PAD MECHANICAL DATA

## PWP (R-PDSO-G20) PowerPAD™ SMALL PLASTIC OUTLINE

### THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



Top View

Exposed Thermal Pad Dimensions

4206332-15/AO 01/16

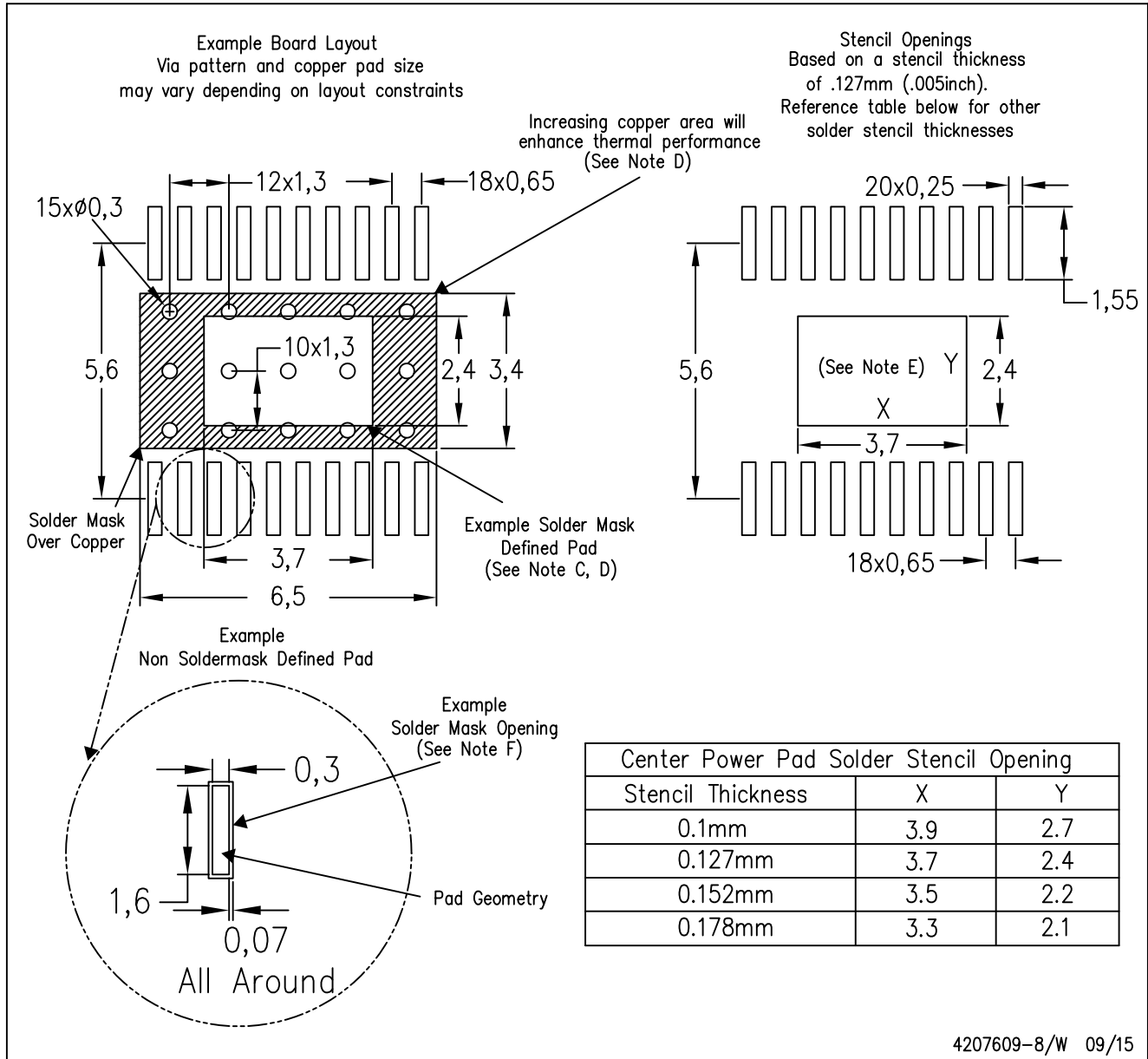
NOTE: A. All linear dimensions are in millimeters

 Exposed tie strap features may not be present.

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PWP (R-PDSO-G20)

PowerPAD™ PLASTIC SMALL OUTLINE



- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
  - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
  - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
  - F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

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